

Tobit models for count time series



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Introduction

Count process $(X_t)_{t \in \mathbb{Z} = \{\dots, -1, 0, 1, \dots\}}$ with range $\mathbb{N}_0 = \{0, 1, \dots\}$ or $\{0, \dots, N\}$ (unbounded vs. bounded counts).

Many ARMA-like model for count time series, e. g., integer-valued ARMA (**INARMA**) using “thinning operators” (McKenzie, 1985; Alzaid & Al-Osh, 1990; Du & Li, 1991; . . .), or integer-valued generalized AR conditional heteroscedasticity (**INGARCH**) via conditional mean (Ferland et al., 2006; Xu et al., 2012; Zhu, 2012; . . .), see Weiß (2018) for survey.

Common drawback: not able to explain negative ACF values!

How achieve negative ACF values?

- ... within INGARCH framework:
 - use (highly) non-linear link function, e. g.,
log-linear model as in Fokianos & Tjøstheim (2011);
 - use nearly linear link function, e. g.,
softplus model as in Weiß et al. (2022);
- ... within INARMA framework: ???

Our proposal (across different model classes):

Tobit approach (“Tobin’s probit”, see Tobin (1958)).

General Tobit approach: given process' past $X_{t-1}, \dots$,
define integer auxiliary r.v. Y_t with support $\mathbb{Z}$,
define X_t by left-censoring at zero: $X_t = \max\{0, Y_t\}$.

Special cases:

- Tobit INGARCH model like in Weiß & Zhu (2025);
- Tobit INARMA models, work in progress
together with Fukang Zhu and Hee-Young Kim.

Outline: model proposals and stochastic properties,
parameter estimation and data applications.



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(Skellam) Tobit INGARCH Models

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Definition & Properties

INGARCH models generally defined by linear conditional mean:

$$M_t = a_0 + \sum_{i=1}^p a_i X_{t-i} + \sum_{j=1}^q b_j M_{t-j}.$$

Then, X_t emitted by conditional count distribution,

where $M_t := E(X_t | X_{t-1}, \dots) > 0$ must be ensured

$\Rightarrow$ parameter constraints $a_0 > 0$ and $a_1, \dots, a_p, b_1, \dots, b_q \geq 0$

$\Rightarrow$ only positive ACF values.

INGARCH models generally defined by linear conditional mean:

$$M_t = \alpha_0 + \sum_{i=1}^p \alpha_i X_{t-i} + \sum_{j=1}^q \beta_j M_{t-j}.$$

Tobit INGARCH models:

Let $\mathcal{S}_\nu(\mu)$ be $\mathbb{Z}$ -valued random operator, where $\mu \in \mathbb{R}$ is mean of $\mathcal{S}_\nu(\mu)$ and ν comprises further parameters. We assume that $P(\mathcal{S}_\nu(\mu) > 0) > 0$ for all μ and ν .

Then, $X_t = \max\{0, Y_t\}$ with $Y_t = \mathcal{S}_\nu(M_t)$.

Note: $M_t := E(Y_t | X_{t-1}, \dots)$ allowed to become negative, so $\alpha_1, \dots, \alpha_p, \beta_1, \dots, \beta_q$ may be negative as well!

Skellam distribution = Poisson difference distribution, i. e.,
 $Y \sim \text{Sk}(\lambda_1, \lambda_2)$ iff $Y = X_1 - X_2$ with independent $X_i \sim \text{Poi}(\lambda_i)$.
Its mean and variance are $\mu = \lambda_1 - \lambda_2$, $\sigma^2 = \lambda_1 + \lambda_2 > |\mu|$.

Proposition: If $Y \sim \text{Sk}(\lambda_1, \lambda_2)$, then partial moments

$$E(\max\{0, Y\}) = \mu P(Y \geq 0) + \lambda_2 (P(Y = 0) + P(Y = 1))$$

and $E(\max\{0, Y\}^2) =$

$$(\sigma^2 + \mu^2) P(Y \geq 1) + \lambda_2 \mu P(Y = 1) + \lambda_1 (1 + \mu) P(Y = 0).$$

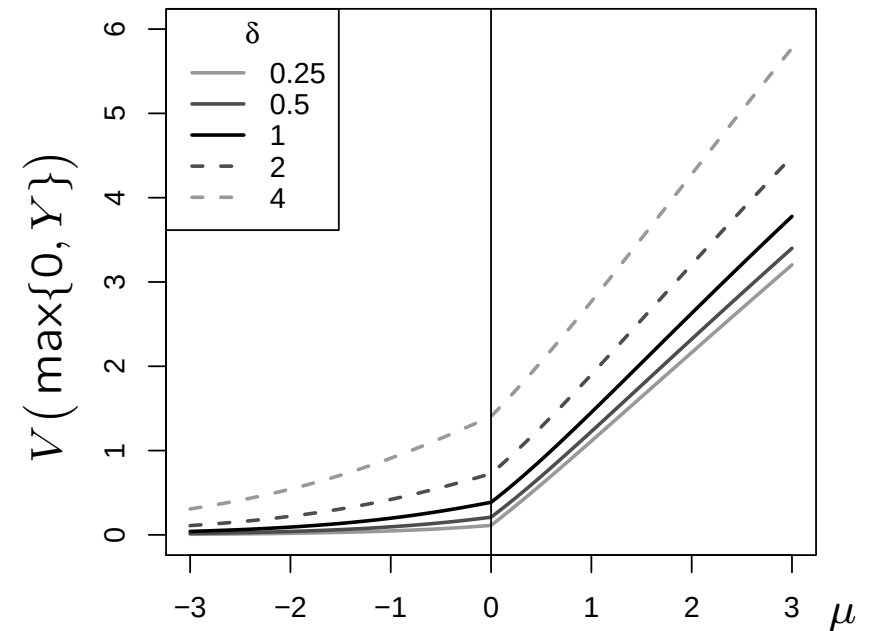
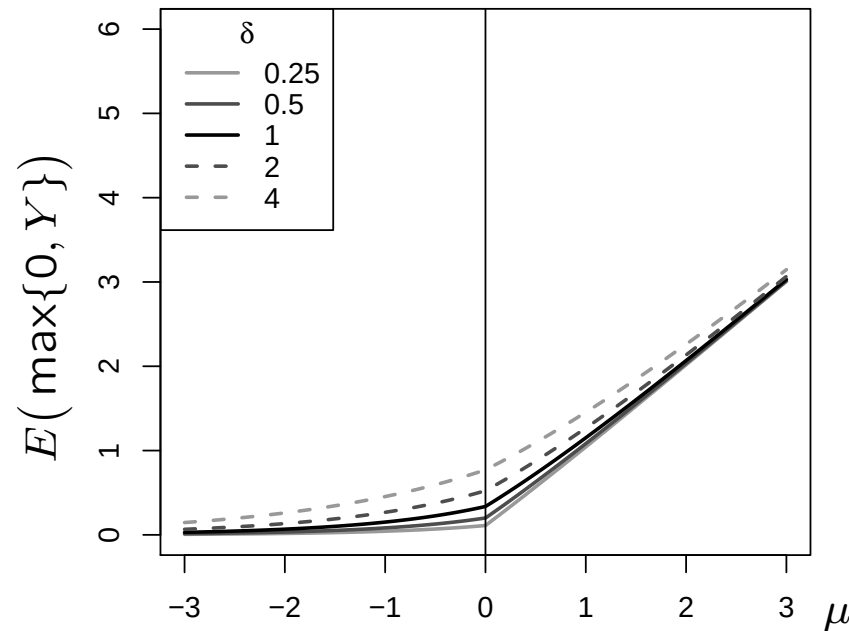
Reparametrization: $\text{Sk}^*(\mu, \delta)$ with $\delta := \sigma^2 - |\mu| > 0$.

Definition: Let $\mathcal{S}_\delta(\mu) \sim \text{Sk}^*(\mu, \delta)$ be **Skellam operator**, then

$$X_t = \max\{0, Y_t\} \quad \text{with} \quad Y_t = \mathcal{S}_\delta(M_t).$$

Theorem: If $\sum_{i=1}^p \max\{0, \alpha_i\} + \sum_{j=1}^q |\beta_j| < 1$,
then STINGARCH process (X_t) exists and is stationary.

Using previous Proposition, it can be shown that
conditional mean and variance approximately piecewise linear,
i. e., STINGARCH process behaves nearly linearly
($\Rightarrow$ Yule–Walker equations for ACF)
and allows for negative ACF at same time!



In Weiß & Zhu (2025), detailed numerical study justifies following approximations if $\delta \leq 0.25$:

$$(p, q) = (1, 0) : \mu \approx \frac{\alpha_0}{1 - \alpha_1}, \quad \frac{\sigma^2}{\mu} \approx \frac{I_{\mu, \delta}^*}{1 - \alpha_1^2}, \quad \rho(h) \approx \alpha_1^h;$$

$$(p, q) = (1, 1) : \mu \approx \frac{\alpha_0}{1 - \alpha_1 - \beta_1},$$

$$\frac{\sigma^2}{\mu} \approx I_{\mu, \delta}^* \cdot \frac{1 - (\alpha_1 + \beta_1)^2 + \alpha_1^2}{1 - (\alpha_1 + \beta_1)^2},$$

$$\rho(h) \approx (\alpha_1 + \beta_1)^{h-1} \frac{\alpha_1 (1 - \beta_1(\alpha_1 + \beta_1))}{1 - (\alpha_1 + \beta_1)^2 + \alpha_1^2},$$

where $I_{\mu, \delta}^* := V(\max\{0, Y\}) / E(\max\{0, Y\})$ for $Y \sim \text{Sk}^*(\mu, \delta)$.

$\Rightarrow$ STINGARCH models as “workhorse”

for linear count processes with signed ACF values.

(Bounded) Tobit INARMA Models

(work in progress)

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Definition & Properties

We adapt the **signed INAR model** of Kim & Park (2008), which uses “signed binomial thinning” operator “ $\odot$ ”:

$$\alpha \odot X = \text{sgn}(\alpha) \cdot (|\alpha| \circ X), \quad \text{where } |\alpha| \circ X \sim \text{Bin}(X, |\alpha|).$$

TINAR model:

$$X_t = \max\{0, Y_t\}, \quad Y_t = \alpha_1 \odot X_{t-1} + \dots + \alpha_p \odot X_{t-p} + \epsilon_t,$$

where (ϵ_t) i. i. d. count innovations.

Theorem: If all roots of polynomial equation

$$z^p - \alpha_1 z^{p-1} - \dots - \alpha_{p-1} z - \alpha_p = 0 \quad \text{inside unit circle,}$$

then TINAR process (X_t) is stationary and ergodic.

Example: Let $\mathcal{B}_{N,\pi} \sim \text{Bin}(N, \pi)$. For TINAR(1) model,

$$P(X_t = x > 0 \mid X_{t-1}) = \sum_{i=0}^{X_{t-1}} P(\mathcal{B}_{X_{t-1}, |\alpha_1|} = i) \cdot f_\epsilon(x - \text{sgn}(\alpha_1) i),$$

$$P(X_t = 0 \mid X_{t-1}) = \sum_{i=0}^{X_{t-1}} P(\mathcal{B}_{X_{t-1}, |\alpha_1|} = i) \cdot F_\epsilon(-\text{sgn}(\alpha_1) i),$$

where F_ϵ is cdf of ϵ_t , and $F_\epsilon(y) = 0$ if $y < 0$.

If $\alpha_1 = -a_1 < 0$, then conditional mean nearly piecewise linear:

$$E[X_t \mid X_{t-1}] = \mu_\epsilon - a_1 X_{t-1} + \sum_{i=0}^{X_{t-1}} P(\mathcal{B}_{X_{t-1}, a_1} = i) E[(i - \epsilon_t) \mathbb{1}(\epsilon_t \leq i)].$$

Numerical study shows AR(1)-like ACF also for $\alpha_1 < 0$.

TINMA model:

$$\begin{aligned} X_t &= \max\{0, Y_t\}, \quad Y_t = \epsilon_t + \beta_1 \odot \epsilon_{t-1} + \dots + \beta_q \odot \epsilon_{t-q} \\ &= \epsilon_t + \sum_{i \in \mathcal{P}} \beta_i \circ \epsilon_{t-i} - \sum_{j \in \mathcal{N}} |\beta_j| \circ \epsilon_{t-j}, \end{aligned}$$

where $\mathcal{N} = \{1 \leq i \leq q \mid \beta_i < 0\}$, $\mathcal{P} = \{1, \dots, q\} \setminus \mathcal{N}$.

Example: For Poi-TINMA model, Y_t has Skellam distribution:

$$Y_t \sim \text{Sk}(\lambda_1, \lambda_2) \quad \text{with } \lambda_1 = \mu_\epsilon (1 + \sum_{i \in \mathcal{P}} \beta_i), \quad \lambda_2 = \mu_\epsilon \sum_{j \in \mathcal{N}} |\beta_j|.$$

Together with above Proposition from Weiß & Zhu (2025),
explicit expressions for mean and variance of X_t ,
also closed formula for lag-1 ACF of Poi-TINMA(1) model.

If (X_t) has bounded range $\{0, \dots, N\}$,
we define **BTINARMA process** via

$$\begin{aligned} X_t &= \min \{N, \max\{0, Y_t\}\}, \\ Y_t &= \alpha_1 \odot X_{t-1} + \dots + \alpha_p \odot X_{t-p} \\ &\quad + \epsilon_t + \beta_1 \odot \epsilon_{t-1} + \dots + \beta_q \odot \epsilon_{t-q}, \end{aligned}$$

where innovations (ϵ_t) i. i. d. with range $\{0, \dots, N\}$.

Theorem: If $|\alpha_1|, \dots, |\beta_q| \in (0; 1)$ and $P(\epsilon_t = y) > 0$ for all y ,
then BTINARMA process (X_t) is stationary and ergodic.

Parameter Estimation and Application

(work in progress)

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Data Example

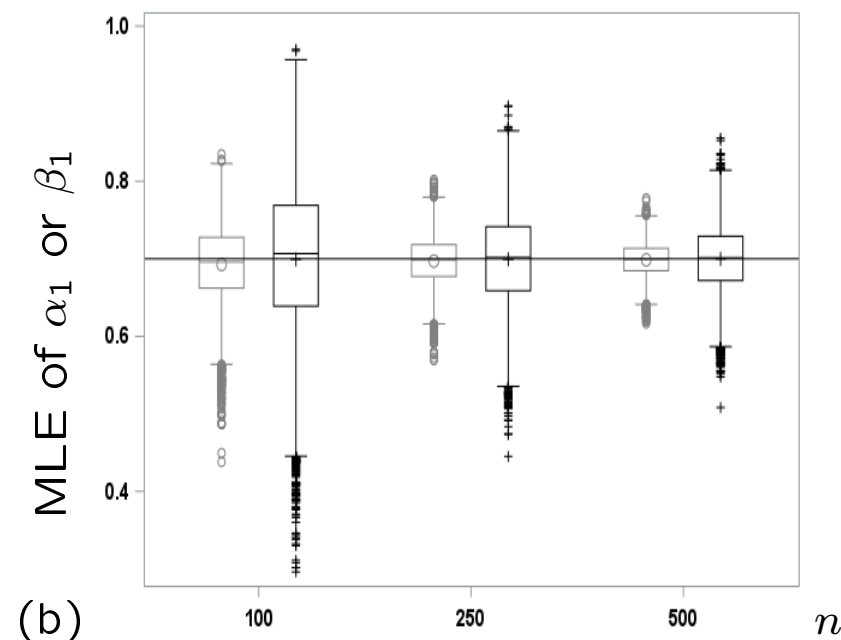
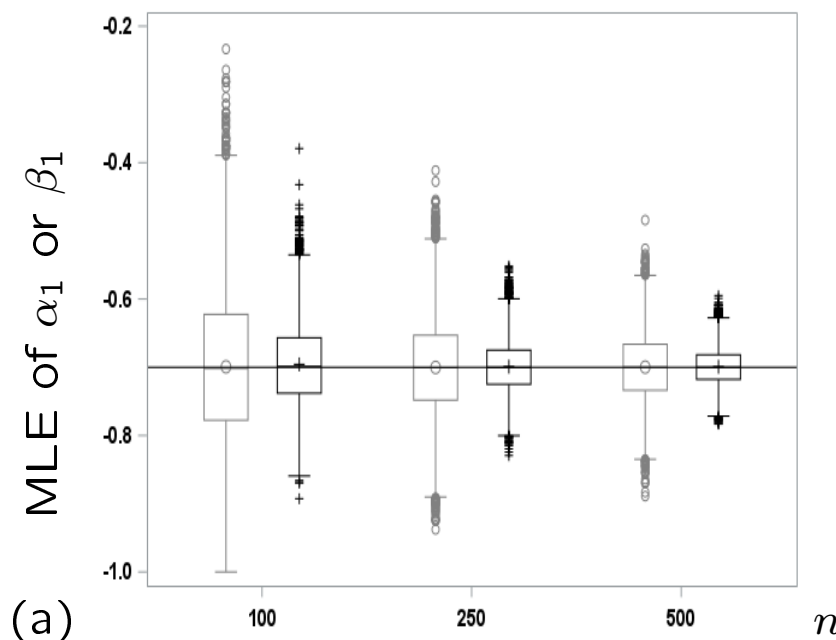
For all types of Tobit model,

maximum likelihood (ML) estimation possible:

- TINGARCH and TINAR have closed-form conditional distribution, so conditional ML estimation;
- for TINMA, forward algorithm known from Hidden-Markov models can be adapted;
- BTINARMA possesses a Markov-chain representation.

For TINGARCH and TINAR, we also analyzed censored least absolute deviations estimation (CLADE), but ML estimation superior performance.

MLE $\hat{\alpha}_1$ of TINAR(1) (left) and $\hat{\beta}_1$ of TINMA(1) (right):



(a) $(\mu_{\text{appr}}, \alpha_1) = (2.5, -0.7) = (\mu_{\text{appr}}, \beta_1)$;

(b) $(\mu_{\text{appr}}, \alpha_1) = (2.5, 0.7) = (\mu_{\text{appr}}, \beta_1)$.

Three data examples in Weiß & Zhu (2025). Here:

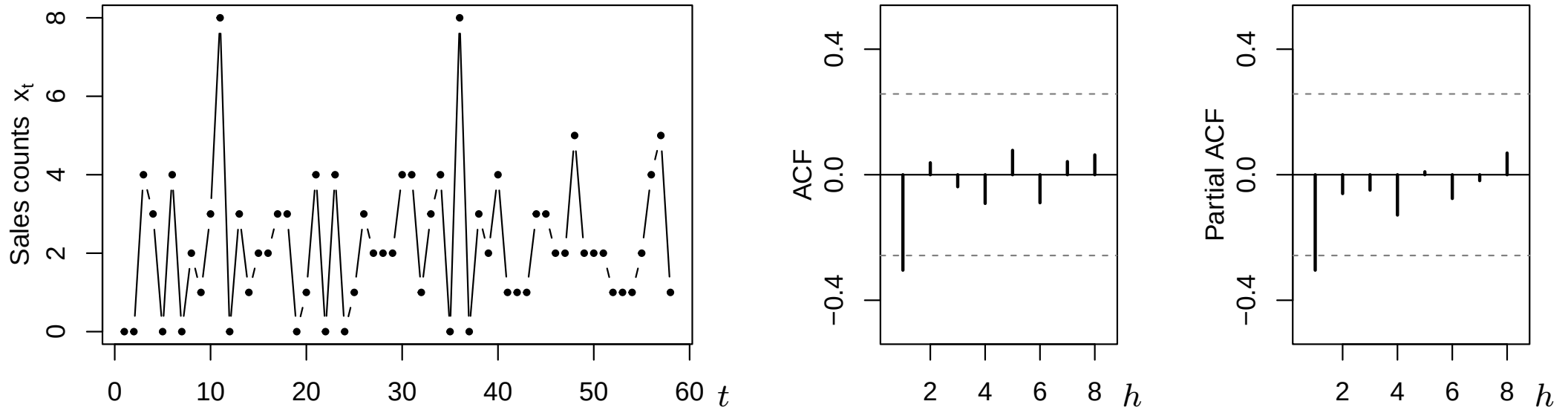
Example: Weekly Sales of Beer.

Weekly counts $x_1, \dots, x_{58}$ of sold items of “SIERRA NEVADA STOUT (6/12 O)” in period March 28, 1996, to May 7, 1997, taken from Dominick’s Data.

Sample mean ≈ 2.241 and variance ≈ 3.239 (overdispersion).

AR(1)- or MA(1)-like ACF

with negative lag-1 value ≈ -0.304 : ...



We start with three AR(1)-like candidate models:

- softplus Poi-spINARCH(1) from Weiß et al. (2022),
- Sk-TINARCH(1) from Weiß & Zhu (2025),
- and Poi-TINAR(1).

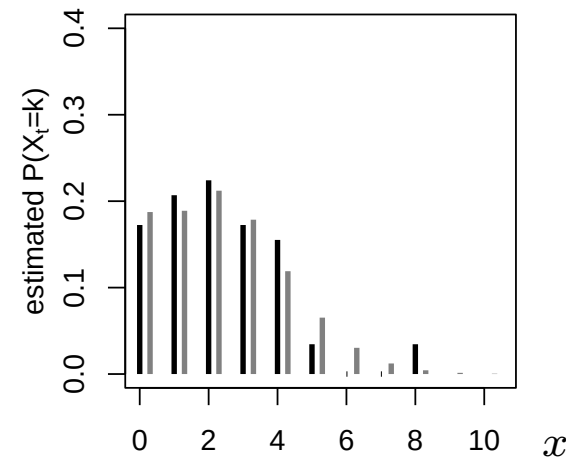
	Par. 1	Par. 2	AIC	BIC	Model fit's		Pear. resid.'s	
					mean	var	mean	var
Poi-spINARCH(1)	3.099 (0.398)	−0.421 (0.136)	216.3	220.4	2.181	2.651	−0.007	1.332
Sk-TINARCH(1)	3.178 (0.017)	−0.397 (0.005)	214.1	218.2	2.274	2.892	−0.005	1.224
Poi-TINAR(1)	2.915 (0.365)	−0.326 (0.147)	214.8	218.9	2.271	3.158	−0.001	0.993

spINARCH(1) outperformed by TINARCH(1) and TINAR(1) in terms of AIC and BIC.

TINAR(1) better agreement to sample mean ≈ 2.241 and variance ≈ 3.239 , also superior concerning Pearson residuals.

Poi-TINAR(1) best among
AR(1)-like models.

Also marginal distribution
close to sample pmf:



Poi-TINMA(1) similarly well concerning marginal properties,

ML estimates (s. e. in parentheses):

$\hat{\mu}_\epsilon \approx 2.965$ (0.416), $\hat{\beta}_1 \approx -0.261$ (0.103).

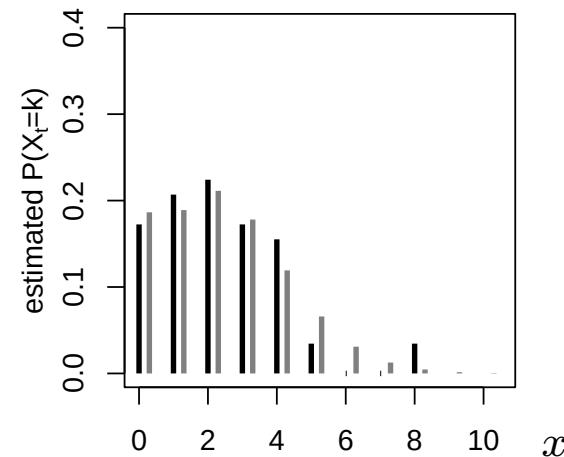
Maximized log-likelihood: -103.6 .

Fitted Poi-TINMA(1) model's

mean: 2.281 (sample: 2.241),

variance: 3.188 (sample: 3.239),

lag-1 acf: -0.183 (sample: -0.304).



... but worse regarding lag-1 ACF, so TINAR(1) preferable!

- Tobit approach applicable across model families.
- Tobit INGARCH and INARMA models allow for negative ACF, but still behave nearly like linear models.
- ML estimation performs well for TINGARCH and TINARMA.

Ongoing research:

- For BTINARMA models (bounded counts), still model properties need to be derived, estimation approaches not investigated so far.

Thank You for Your Interest!



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