

Approximately Linear INGARCH Models for Spatio-Temporal Counts



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Approximately Linear INGARCH Models for Count Time Series

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Introduction

Count processes (X_t) : range contained in \mathbb{N}_0 ,
i. e., set of *non-negative* integers (see Weiß, 2018).

Distinguish **two cases**:

- **unbounded** counts (X_t) , i. e., full \mathbb{N}_0 as range;
- **bounded** counts (X_t) , i. e., upper bound $n \in \mathbb{N}$,
so range $\{0, \dots, n\}$ also bounded from above!

(Exactly linear) **INGARCH model** (Ferland et al., 2006)

for **unbounded** counts (X_t) : Let $M_t = E[X_t | \mathcal{F}_{t-1}]$, then

$$M_t = a_0 + \sum_{i=1}^p a_i X_{t-i} + \sum_{j=1}^q b_j M_{t-j}.$$

Counts $X_t | \mathcal{F}_{t-1}$ emitted by, for example, $\text{Poi}(M_t)$.

(Exactly linear) **BINGARCH model** (Ristić et al., 2016)

for **bounded** counts (X_t) : Let $P_t = \frac{1}{n} M_t$, then

$$P_t = a_0 + \sum_{i=1}^p a_i X_{t-i}/n + \sum_{j=1}^q b_j P_{t-j}.$$

Counts $X_t | \mathcal{F}_{t-1}$ emitted by, for example, $\text{Bin}(n, P_t)$.

Problem: *In both cases, rather limiting parameter constraints that prevent negative parameter and ACF values.*

Possible solution: approximately linear (B)INGARCH models by Weiß et al. (2022), Weiß & Jahn (2021), with negative ACF values while (nearly) linear model structure.

Solution by Weiß et al. (2022) for unbounded counts:
softplus INGARCH model with response function $f = \text{sp}_c$.

Softplus function

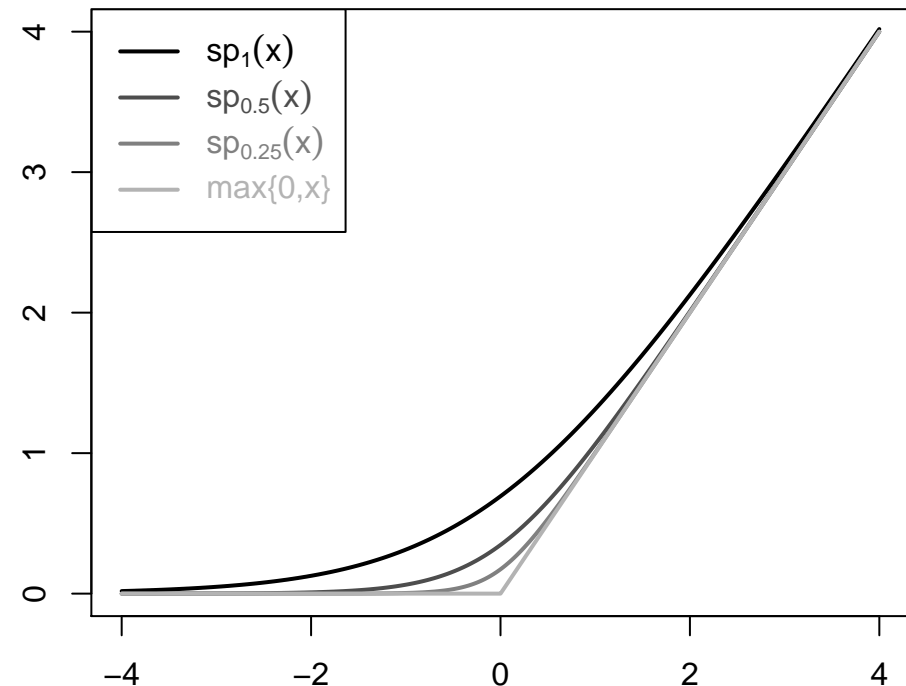
$$\text{sp}_c(x) = c \ln(1 + \exp(x/c))$$

with tuning parameter $c > 0$,

truly positive

and differentiable;

spINGARCH model:



$$M_t = \text{sp}_c\left(\alpha_0 + \sum_{i=1}^p \alpha_i X_{t-i} + \sum_{j=1}^q \beta_j M_{t-j}\right).$$

Solution by Weiß & Jahn (2021) for bounded counts:
soft-clipping BINGARCH with response fct. $f = sc_c$.

Soft-clipping function

$$sc_c(x) = c \ln \left(\frac{1 + \exp(\frac{x}{c})}{1 + \exp(\frac{x-1}{c})} \right)$$

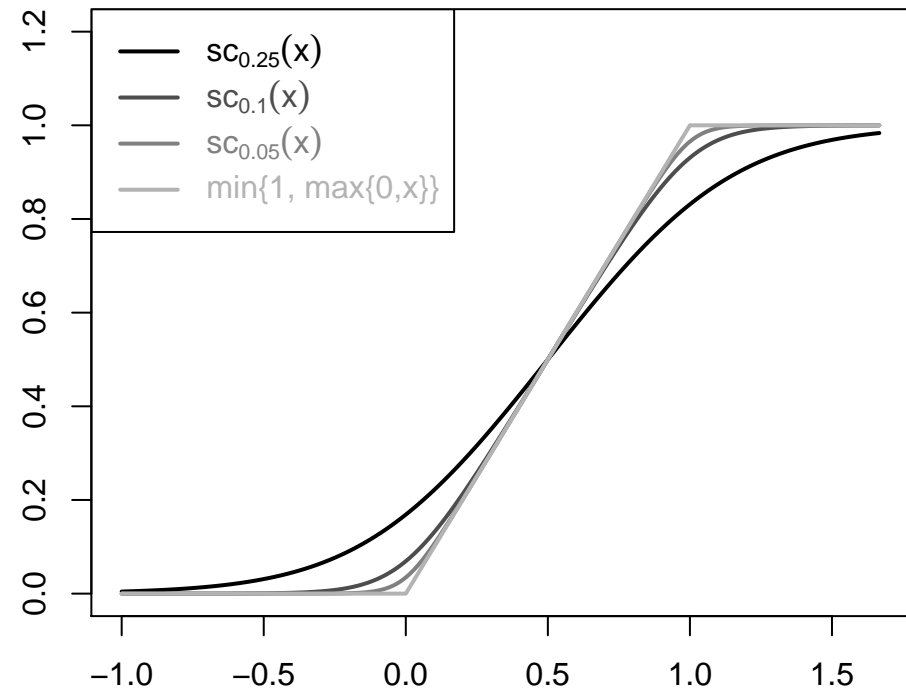
with tuning parameter $c > 0$,

truly in $(0; 1)$

and differentiable;

scBINGARCH model:

$$P_t = sc_c \left(\alpha_0 + \sum_{i=1}^p \alpha_i X_{t-i}/n + \sum_{j=1}^q \beta_j P_{t-j} \right).$$





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On Linear Spatio-Temporal INGARCH Models

Existing Literature

Up to now, spatio-temporal (ST) models for unbounded counts, mainly applications in epidemiology (disease surveillance).

Let $\mathbf{X}_t = (X_{t,1}, \dots, X_{t,m})^\top \in \mathbb{N}_0^m$, $m \in \mathbb{N}$, express count $X_{t,i}$ at time t in unit i . For INGARCH-type models, denote conditional mean $M_{t,i}$, used for generating $X_{t,i} | \mathcal{F}_{t-1}$.

ST-INARCH(1) model (Held et al., 2005; Paul et al., 2008):

$$M_{t,i} = \lambda_i X_{t-1,i} + \phi_i \sum_{j \neq i} w_{ji} X_{t-1,j} + \gamma_i,$$

where, e. g., spatial weights $w_{ji} = 0$ if unit j not neighbour of i , otherwise $w_{ji} = 1/n_j$ (row-normalized, $n_j = \text{neighbours of } j$).

ST-INARCH(1) model in matrix notation: $\mathbf{M}_t = \mathbf{\Gamma} \mathbf{X}_{t-1} + \gamma$,
where $\mathbf{\Gamma}$ diagonal entries λ_i and off-diagonal entries $\phi_i w_{ji}$,
see Held & Paul (2012).

Armiliotta & Fokianos (2021): unique λ, ϕ, γ across locations i .

Higher-order extension by Bracher & Held (2020):

$$\mathbf{M}_t = \sum_{k=1}^p u_k \mathbf{\Gamma} \mathbf{X}_{t-k} + \gamma,$$

where AR-weights u_1, \dots, u_p with $\sum_{k=1}^p u_k = 1$, e. g.,

$u_k \sim \kappa^{k-1}$ such that INGARCH(1, 1)-type model for $p \rightarrow \infty$.

ST-INGARCH(1, 1) by Clark & Dixon (2021):

$\mathbf{M}_t = \gamma_t + a_1 \mathbf{X}_{t-1} + b_1 \mathbf{M}_{t-1}$, i. e., with scalar coefficients.

Problems:

- All model parameters non-negative (to ensure $M_{t,i} > 0$), thus only positive ACF values can be captured.
- No proposal for bounded counts.

Our contributions:

- ST softplus INGARCH($p, r; q, s$) (ST-spINGARCH) for unbounded counts – simulations and illustration;
- ST soft-clipping BINGARCH($p, r; q, s$) (ST-scBINGARCH) for bounded counts, applied to meteorological time series, solving problems we are confronted with in practice.



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The Spatio-Temporal Softplus INGARCH Model for Unbounded Counts

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 Definition & Discussion ▪

ST-spINGARCH($p, r; q, s$) model with range \mathbb{N}_0^m :

$$M_{t,i} = \text{sp}_c \left(\alpha_0 + \sum_{k=1}^p \alpha_k X_{t-k,i} + \sum_{g=1}^r \lambda_g \sum_{j \neq i} w_{ij} X_{t-g,j} \right. \\ \left. + \sum_{l=1}^q \beta_l M_{t-l,i} + \sum_{h=1}^s \phi_h \sum_{j \neq i} w_{ij} M_{t-h,j} \right), \quad i = 1, \dots, m,$$

where $X_t | \mathcal{F}_{t-1}$ emitted by

multivariate unbounded-counts distribution with mean M_t .

Default choice: (conditionally) independent Poisson.

Possible extensions: copula for stronger cross-correlation;

different distribution family, e. g., negative binomial;

time- or unit-specific parameters.

Model fitting: CML estimation.

If feedback terms included in model,
then initialization of (M_t) by mean \bar{X} .

CML estimates computed by numerical optimization routine,
approximate standard errors via inverse Hessian.

Model selection via Akaike's information criterion (AIC).

Simulation study: 1,000 repl., “ k -nearest neighbours” (knn).

$m = 20$ Cartesian coordinates $\mathbf{u}_i = (x_i, y_i)$ randomly per simulation run, then knn spatial weights with $k = 5$:

$w_{ji} = 1/5$ if \mathbf{u}_j one of five nearest points of \mathbf{u}_i .

Simulation scenarios ($T = 100, 250, 500, 1000$):

Model		α_0	α_1	α_2	λ_1	λ_2	β_1	ϕ_1
ST-spINGARCH(1, 1; 0, 0)	model I	3	0.4		0.2			
	model II	3	-0.4		0.2			
ST-spINGARCH(2, 2; 0, 0)	model III	1.5	0.1	0.15	0.2	0.3		
	model IV	1.5	-0.1	0.15	0.2	0.3		
ST-spINGARCH(1, 1; 1, 1)	model V	1.5	0.1		0.15		0.2	0.3
	model VI	1.5	0.3		0.15		0.2	-0.1

Summary of findings:

Bias and RMSE decrease as T increases (consistency).

CML estimates for AR-type models (1, 1; 0, 0) and (2, 2; 0, 0) converge faster than for feedback model (1, 1; 1, 1).

Illustrative application: Chicago crime data.

Monthly number of burglaries ($T = 72$) in $m = 552$ census block groups, see Clark & Dixon (2021). Two blocks are neighbours if they share border. Spatial weights $w_{ji} = 1/n_j$ if i is adjacent to j ($n_j =$ number of neighbours of j).

Armigliotta & Fokianos (2021) fit first- and second-order “Poisson network autoregression” (PNAR) model (linear or log-linear). Information criteria prefer linear models, best performance by PNAR(2) model.

Illustrative application: Chicago crime data.

Using Poi-ST-spINGARCH(1, 1; 0, 0)–(2, 2; 0, 0) with $c = 0.01$, nearly identical estimates as for exactly linear PNAR models:

	α_0	α_1	λ_1	α_0	α_1	α_2	λ_1	λ_2
est. coeff.	0.4550	0.2835	0.3215	0.3207	0.2286	0.1626	0.2077	0.1191
approx. SE	0.0082	0.0048	0.0070	0.0088	0.0049	0.0048	0.0079	0.0078

Thus, Poi-ST-spINGARCH model behaves linear in close approximation.

(...)

Illustrative application: Chicago crime data.

By contrast to PNAR model, we can include feedback term:

	α_0	α_1	α_2	λ_1	λ_2	β_1	ϕ_1
est. coeff.	0.0064	0.1004	-0.0892	0.1620	-0.1160	0.9824	-0.0515
approx. SE	0.0012	0.0037	0.0030	0.0054	0.0057	0.0024	0.0031

Softplus link useful as negative values for $\alpha_2, \lambda_2, \phi_1$.

Large drop in magnitude of (non-)spatial AR coefficients, nearly all “dependency mass” into non-spatial feedback term β_1 , so slowly decaying ACF.

Seems to indicate non-stationarity: negative trend in data.



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The Spatio-Temporal Soft-clipping BINGARCH Model for Bounded Counts

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Definition & Discussion

ST-scBINGARCH($p, r; q, s$) model with range $\{0, \dots, n\}^m$:

$$P_{t,i} = \text{sc}_c \left(\alpha_0 + \sum_{k=1}^p \alpha_k X_{t-k,i}/n + \sum_{g=1}^r \lambda_g \sum_{j \neq i} w_{ij} X_{t-g,j}/n \right. \\ \left. + \sum_{l=1}^q \beta_l P_{t-l,i} + \sum_{h=1}^s \phi_h \sum_{j \neq i} w_{ij} P_{t-h,j} \right), \quad i = 1, \dots, m,$$

where $X_t | \mathcal{F}_{t-1}$ emitted by

multivariate bounded-counts distribution with mean $n \cdot P_t$.

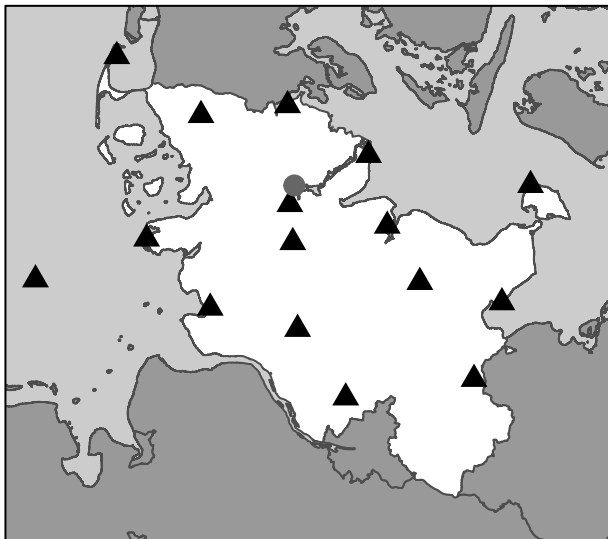
Default choice: (conditionally) independent binomials.

Possible extensions: copula for stronger cross-correlation;
different distribution family, e. g., zero-inflated binomial (ZIB).

Parameter estimation by conditional ML approach.

Applied to meteorological t. s. (DWD Climate Data Center),
for weather stations in Schleswig-Holstein:

cloud coverage data ($m = 17$): precipitation data ($m = 34$):



grey circle = weather station "Schleswig"



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Cloud Coverage: Dealing with Missing Values

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Data Application

Hourly cloud-coverage data (2009–2019), i. e.,
share of visible sky covered by clouds.

Counts (“okta”) from 0 (no clouds) to 8 (sky fully overcast),
i. e., counts $X_{t,i}$ with bound $n = 8$.

Irregular observations:

flag “9” (no data), “-1” (sky not observable),
treated as “NA” (not available, i. e., missing data).

5.5 % of NA observations in $\{x_{t,i}\}$. But

57.2 % of vectors x_t with at least one NA component $x_{t,i}$.

⇒ We have to **impute integer values!**

Our solution: If $x_{t,i}$ missing, then

impute with value $x_{t,j}$ from most correlated non-NA station at time t (thus preserving integer nature of data).

Selected $x_{t,j} \approx$ “nearest neighbour” in terms of cross-correlation.

Average maximum corr. between stations over time is 0.709.

Our proposal for **spatial weight matrix** $\mathbf{W} = (w_{ij})_{i,j=1,\dots,m}$:

rely on great circle distance d_{ij} , with two extreme cases:

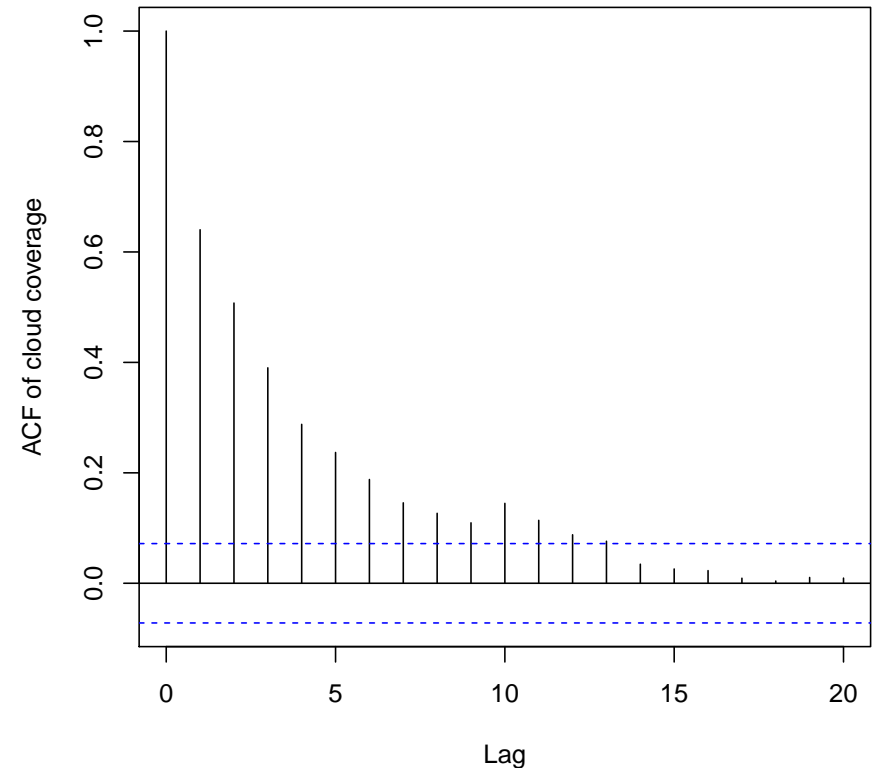
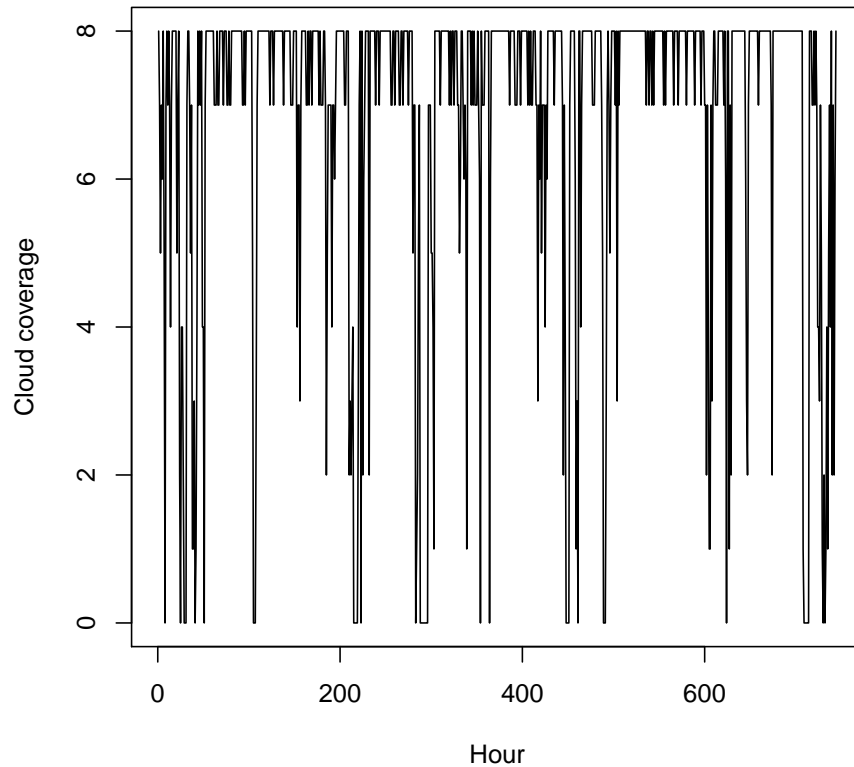
- sparse $\mathbf{W}^{(1)}$: only nearest neighbour,

$$w_{ij}^{(1)} = 1 \text{ if } j \text{ geographically closest to } i;$$

- dense $\mathbf{W}^{(2)}$: all neighbours,

$$w_{ij}^{(2)} = 1/d_{ij} \text{ plus row-normalization.}$$

Example: Hourly cloud coverage at “Schleswig”, Dec. 2019:



⇒ slowly decaying memory,
use feedback terms in ST-scBINGARCH model.

For both $\mathbf{W}^{(1)}$ and $\mathbf{W}^{(2)}$, model selection via AIC.

$\mathbf{W}^{(2)}$ generally produces lower AIC values.

Cloud-coverage counts (Dec. 2019):

ML-fitted ST-scBINGARCH(1, 3; 1, 1) model with $\mathbf{W} = \mathbf{W}^{(2)}$.

	α_0	α_1	λ_1	λ_2	λ_3	β_1	ϕ_1
est. coeff.	0.0725	0.3496	0.6544	0.0909	-0.0637	0.2284	-0.3474
approx. SE	0.0060	0.0070	0.0124	0.0511	0.0089	0.0152	0.0515

Note: negative coefficients, soft-clipping link relevant.

Feedback terms β_1 and ϕ_1 have opposing signs:

“compensation effect”, for ACF of “foreign” stations,

we have faster decay than under pure AR structure.



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Rainy Hours per Day: Accounting for Zero-Inflation

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Data Application

Rainy hours per day: $x_{t,i}$ with upper limit $n = 24$.

Again missing data (0.36 % of total hourly observations),
 but in particular, strong **zero inflation** (38 % of zeros).

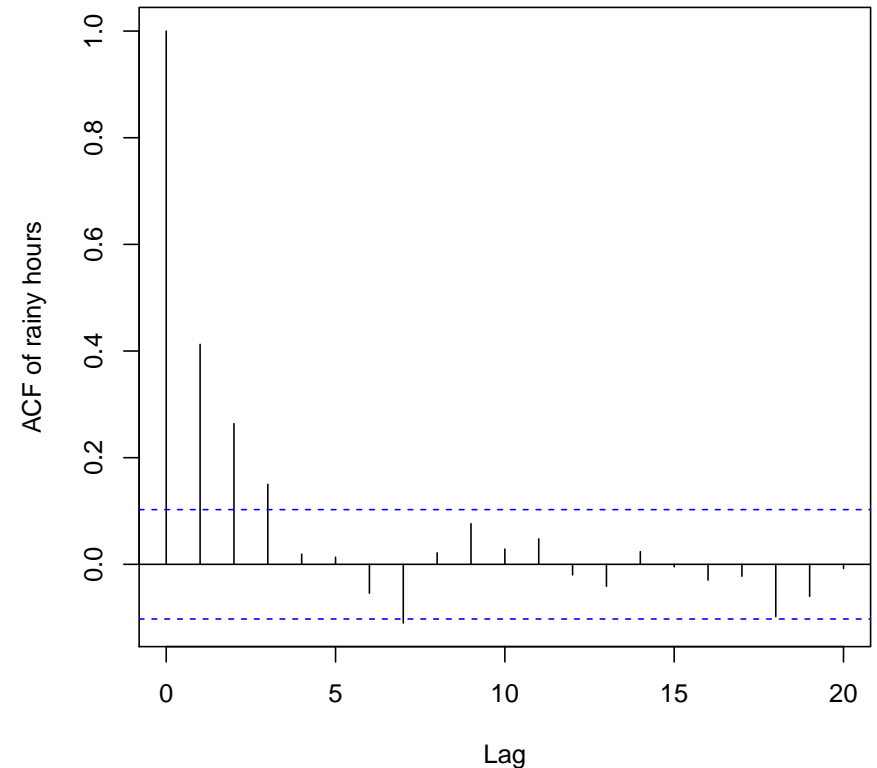
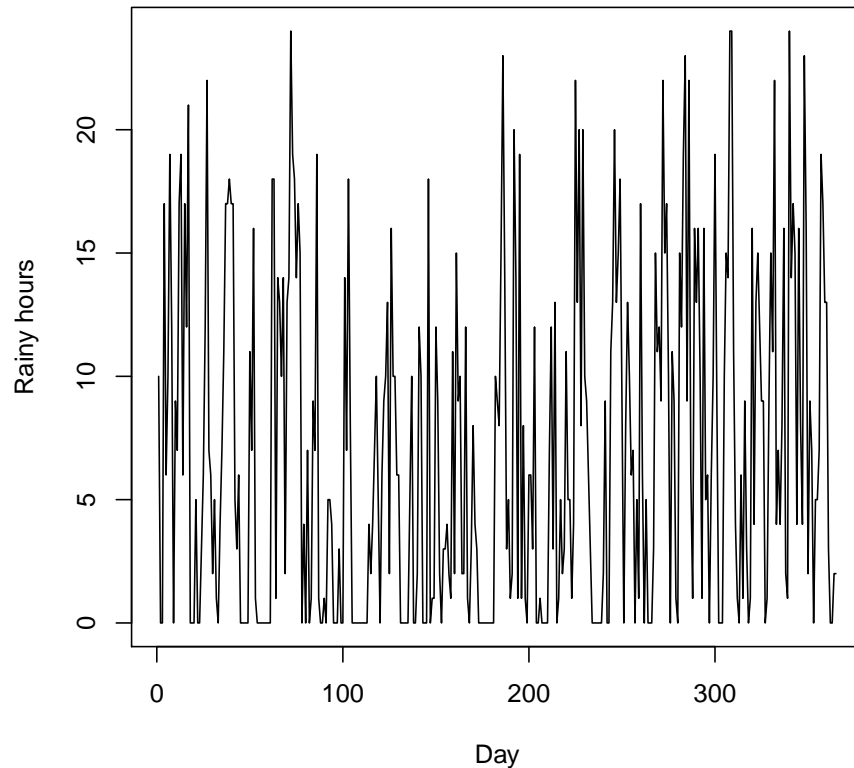
Thus, **conditional ZIB distribution** with parametrization

$$P(X_{t,i} = x | \mathcal{F}_{t-1}) = \omega (1 - P_{t,i}) \mathbb{1}_{\{x=0\}} + (1 - \omega (1 - P_{t,i})) p_{\text{Bin}}\left(x \mid n, \frac{P_{t,i}}{1 - \omega (1 - P_{t,i})}\right).$$

(...) see plots on next slide!

$\mathbf{W} = \mathbf{W}^{(2)}$	ω	α_0	α_1	α_2	α_3	λ_1	λ_2	λ_3
est. coeff.	0.4359	0.1370	0.1863	0.0986	0.1033	0.0336	-0.0396	-0.1057
approx. SE	0.0047	0.0016	0.0074	0.0082	0.0075	0.0086	0.0096	0.0087

Example: Rainy hours per day at “Schleswig” in 2019:



⇒ ACF drops quickly towards zero,
feedback-terms not needed this time.



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Cloud Coverage: Accounting for Cross-Correlation

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Data Application

Default model (conditionally independent binomials)
only moderate cross-correlation.

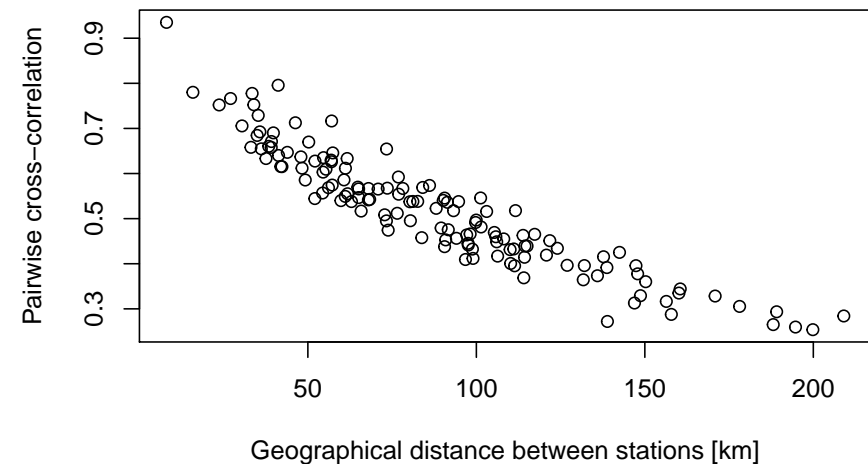
Cloud-coverages (Dec. 2019) with **strong cross-correlation**:

average cross-corr. ≈ 0.52 ,

negative relationship
to geographical distance.

Default model:

cross-correlation ≈ 0.25 .



Idea: like in Armillotta & Fokianos (2021),
employ **copula** distributions with count marginals.

Gaussian copula

$$C(u_1, \dots, u_m) = \Phi_{m; \mathbf{R}}(\Phi^{-1}(u_1), \dots, \Phi^{-1}(u_m))$$

with corresponding copula density

$$c(u_1, \dots, u_m) = \det(\mathbf{R})^{-1/2} \exp\left(\frac{1}{2} \Phi^{-1}(\mathbf{u})^\top (\mathbf{I} - \mathbf{R}^{-1}) \Phi^{-1}(\mathbf{u})\right).$$

With univariate count CDFs F_1, \dots, F_m , joint multivariate CDF

$$F(x_1, \dots, x_m) = C(F_1(x_1), \dots, F_m(x_m)).$$

Problem: joint PMF $p(x_1, \dots, x_m)$ requires

2^m discrete differences of joint CDF, not feasible!

Gaussian copula (. . .)

We use approximate solution of Kazianka & Pilz (2010):

$$p(x_1, \dots, x_m) \approx c(u_1, \dots, u_m) \cdot \prod_{i=1}^m P(X_i = x_i),$$

where $u_i = \frac{1}{2} (F_i(x_i) + F_i(x_i - 1))$ (“mid-point approximation”).

How to choose \mathbf{R} for $\Phi_{m;\mathbf{R}}(\cdot)$?

Standard solution:

“exchangeable correlation structure”, $\mathbf{R} = (1 - \rho)\mathbf{I} + \rho\mathbf{E}$.

How to choose \mathbf{R} for $\Phi_{m;\mathbf{R}}(\cdot)$? (...)

To explicitly account for spatial pattern in cross-correlation, we resort to concept of spatially correlated errors.

Spatial error model (SEM): $\mathbf{y} = f(\mathbf{x}, \boldsymbol{\beta}) + \mathbf{u}$, where $\mathbf{u} = \rho \mathbf{W}\mathbf{u} + \boldsymbol{\epsilon}$ with standard normal $\boldsymbol{\epsilon}$ (LeSage & Pace, 2009).

Error \mathbf{u} as $\mathbf{u} = (\mathbf{I} - \rho \mathbf{W})^{-1} \boldsymbol{\epsilon}$.

With $\mathbf{B} = (\mathbf{I} - \rho \mathbf{W})^{-1}$, resulting covariance matrix $\mathbf{B}\mathbf{B}^\top$.

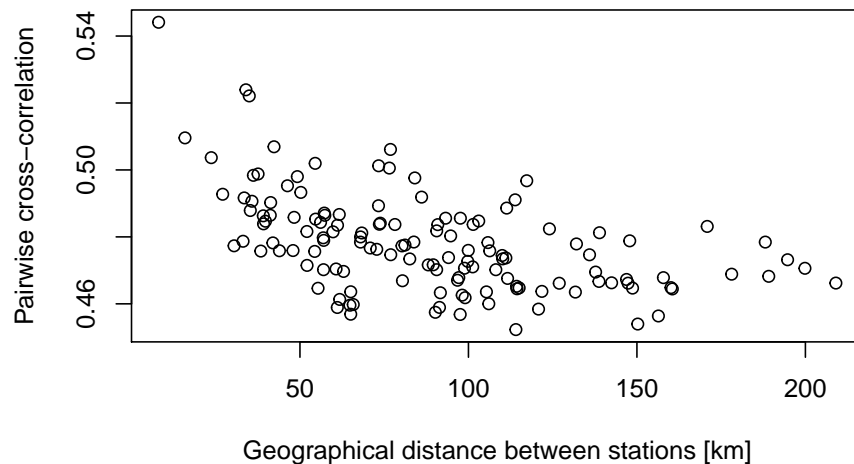
Idea: “SEM copula” with covariance matrix $\mathbf{B}\mathbf{B}^\top$, again single dependence parameter ρ .

SEM-copula ST-scBINGARCH(1, 3; 1, 1) with $\mathbf{W} = \mathbf{W}^{(2)}$:

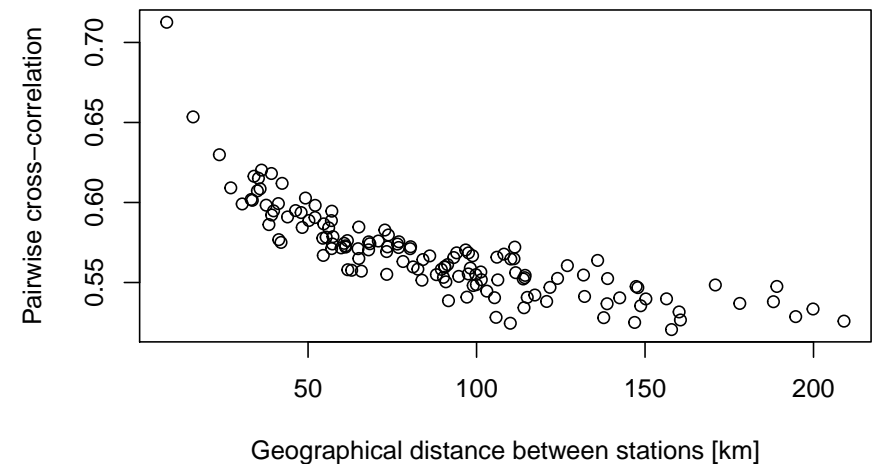
	ρ	α_0	α_1	λ_1	λ_2	λ_3	β_1	ϕ_1
est. coeff.	0.4149	0.0566	0.3452	0.6567	0.0644	-0.0496	0.2335	-0.3181
approx. SE	0.0010	0.0105	0.0079	0.0195	0.0242	0.0211	0.0094	0.0276

Relation between correlation and distance for

standard copula:



SEM copula:



**Thank You
for Your Interest!**



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