

Goodness-of-Fit Testing for Count Time Series



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Introduction

In applications, often testing hypothesis w.r.t.

marginal distribution of given count time series X_1, \dots, X_T .

Might be done by

- looking at specific feature of hypothetical count distribution, e. g., Poisson index of dispersion (Schweer & Weiß, 2014);
- deriving test statistic considering any deviation from null model, e. g., based on pgf (Meintanis & Karlis, 2014).

Textbook approach:

GoF statistics based on hypothetical & estimated **pmf**, e. g., power-divergence family (Read & Cressie, 1988).

Many common GoF tests within power-divergence family.

Since asymptotic behavior same as of **Pearson's GoF statistic** G^2 (Read & Cressie, 1988), focus on latter in sequel.

If X_1, \dots, X_T **i. i. d.**, and if Pearson statistic G^2 constructed by using k categories, then asymptotic χ^2 -distribution:

- if hypothetical distribution fully specified, then G^2 with asymptotic χ_{k-1}^2 -distribution;
- if hypothetical distribution has $r \geq 1$ unspecified parameters to be estimated from data, then G^2 with asymptotic χ_{k-1-r}^2 -distribution.

Aim:

- Develop general approach to *explicitly* compute asymptotic distribution of Pearson's GoF statistic for *serially dependent* count time series,
- covers both scenarios, where model parameters *specified or estimated* from available data.



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Pearson's Goodness-of-Fit Test

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Test Statistic

Let $(X_t)_{\mathbb{Z}}$ stationary count process.

GoF test based on X_1, \dots, X_T to test **hypothesis** H_0 :

marginal distribution satisfies $P(X_t = i) = p_i$ for some pmf $(p_i)_i$.

Following common rules of thumb (Horn, 1977),

first define appropriate **set of categories**,

e. g., of the form (Kim & Weiß, 2015)

$\{0, \dots, a\}, \{a + 1\}, \dots, \{b\}, \{b + 1, \dots\}$ with some $0 \leq a < b$.

Then H_0 -probabilities $\pi = (\pi_a, \dots, \pi_b, \pi_{b+1})^\top$

for X_t falling into these categories

computed from $\mathbf{p} = (p_0, \dots, p_b)^\top$ as (\dots)

$$\boldsymbol{\pi} := \begin{pmatrix} \pi_a \\ \pi_{a+1} \\ \vdots \\ \pi_b \\ \pi_{b+1} \end{pmatrix} := \begin{pmatrix} p_0 + \dots + p_a \\ p_{a+1} \\ \vdots \\ p_b \\ 1 - p_0 - \dots - p_b \end{pmatrix} = \mathbf{A} \mathbf{p} + e_{b-a+2}$$

with $e_{b-a+2} := (0, \dots, 0, 1)^\top$, and

$$\mathbf{A} := \mathbf{A}(a, b) := \left. \begin{pmatrix} 1 & \dots & 1 & 0 & \dots & 0 \\ 0 & \dots & 0 & 1 & \dots & \vdots \\ \vdots & & \vdots & & \dots & 0 \\ 0 & \dots & 0 & 0 & & 1 \\ -1 & \dots & -1 & -1 & \dots & -1 \end{pmatrix} \right\} b - a + 2.$$

$\underbrace{\hspace{10em}}_{a+1}$
 $\underbrace{\hspace{10em}}_{b-a}$

Estimation by relative frequencies: $\hat{p}_i = \frac{1}{T} \sum_{t=1}^T \mathbb{1}_{\{X_t=i\}}$
and $\hat{\pi} := \mathbf{A} \hat{\mathbf{p}} + e_{b-a+2}$ with $\hat{\mathbf{p}} = (\hat{p}_0, \dots, \hat{p}_b)^\top$.

Test statistic of Pearson's GoF test:

$$\begin{aligned} G^2 &= T (\hat{\pi} - \pi)^\top \text{diag}(\pi)^{-1} (\hat{\pi} - \pi) \\ &= T \mathbf{G}^\top \mathbf{G} \quad \text{with } \mathbf{G} := \text{diag}(\pi_a^{-1/2}, \dots, \pi_{b+1}^{-1/2}) \mathbf{A} (\hat{\mathbf{p}} - \mathbf{p}). \end{aligned}$$

Typically, marginal pmf determined by some parameter $\boldsymbol{\theta} \in \mathbb{R}^r$,
i. e., $\mathbf{p} = \mathbf{p}(\boldsymbol{\theta})$ and $\boldsymbol{\pi} = \boldsymbol{\pi}(\boldsymbol{\theta}) = \mathbf{A} \mathbf{p}(\boldsymbol{\theta}) + e_{b-a+2}$.

Pearson's GoF test statistic

$$G^2 = G^2(\hat{p}, \theta).$$

Two scenarios:

- θ specified (so fully specified pmf),
so test statistic $G^2(\hat{p}, \theta)$, or
- θ estimated from X_1, \dots, X_T (GoF with estimated par.),
so test statistic $G^2(\hat{p}, \hat{\theta})$.

For estimation, we use simple moment estimators, i. e.,

$$\theta = h(\mu_1, \dots, \mu_r) \quad \text{and} \quad \hat{\theta} = h(\hat{\mu}_1, \dots, \hat{\mu}_r),$$

where $\mu_k := E[X_t^k]$ with $\mu := \mu_1$

and $\hat{\mu}_k = \frac{1}{T} \sum_{t=1}^T X_t^k$ with $\hat{\mu}_1 = \bar{X}$.



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Asymptotics

Aim: Derive asymptotic distributions of $\sqrt{T} G(\hat{p}, \theta)$ and $\sqrt{T} G(\hat{p}, \hat{\theta})$, respectively, as well as of $G^2(\hat{p}, \theta)$ and $G^2(\hat{p}, \hat{\theta})$.

Step 1: define $(b + 1 + r)$ -dimensional process

$$\mathbf{Z}_t = \begin{pmatrix} \mathbb{1}\{X_t=0\} \\ \vdots \\ \mathbb{1}\{X_t=b\} \\ X_t \\ \vdots \\ X_t^r \end{pmatrix} \quad \text{with} \quad \mu_{\mathbf{Z}} := E[\mathbf{Z}_t] = \begin{pmatrix} p_0 \\ \vdots \\ p_b \\ \mu_1 \\ \vdots \\ \mu_r \end{pmatrix},$$

Assumptions:

- $(X_t)_{\mathbb{Z}}$ is α -mixing with geometrically decreasing weights, and $(2r + \delta)$ -moments with some $\delta > 0$ exist.
- [Property "SYM": $P(X_t = i, X_{t-h} = j)$ symmetric in i, j .]

Under above conditions, with Theorem 1.7 in Ibragimov (1962):

$$\frac{1}{\sqrt{T}} \sum_{t=1}^T (\mathbf{Z}_t - \boldsymbol{\mu}_Z) \xrightarrow{D} N(\mathbf{0}, \boldsymbol{\Sigma}),$$

where

$$\begin{aligned} \sigma_{ij} &= E[Z_{0,i} \cdot Z_{0,j}] - \mu_{Z,i} \mu_{Z,j} \\ &\quad + \sum_{h=1}^{\infty} (E[Z_{0,i} \cdot Z_{h,j}] + E[Z_{h,i} \cdot Z_{0,j}] - 2 \mu_{Z,i} \mu_{Z,j}) \\ &\stackrel{\text{SYM}}{=} E[Z_{0,i} \cdot Z_{0,j}] - \mu_{Z,i} \mu_{Z,j} + 2 \sum_{h=1}^{\infty} (E[Z_{h,i} \cdot Z_{0,j}] - \mu_{Z,i} \mu_{Z,j}). \end{aligned}$$

Under above conditions, with Theorem 1.7 in Ibragimov (1962):

$$\frac{1}{\sqrt{T}} \sum_{t=1}^T (\mathbf{Z}_t - \boldsymbol{\mu}_Z) \xrightarrow{D} \mathbf{N}(\mathbf{0}, \boldsymbol{\Sigma}).$$

If $\boldsymbol{\theta}$ specified:

$$\sqrt{T} (\hat{\mathbf{p}} - \mathbf{p}) \xrightarrow{D} \mathbf{N}(\mathbf{0}, \boldsymbol{\Sigma}^{(p)}) \quad \text{with } \boldsymbol{\Sigma}^{(p)} := (\sigma_{ij})_{i,j=0,\dots,b}.$$

If $\boldsymbol{\theta}$ estimated, $\hat{\boldsymbol{\theta}} = \mathbf{h}(\hat{\mu}_1, \dots, \hat{\mu}_r)$:

$$\sqrt{T} ((\hat{\mathbf{p}}, \hat{\boldsymbol{\theta}}) - (\mathbf{p}, \boldsymbol{\theta})) \xrightarrow{D} \mathbf{N}(\mathbf{0}, \boldsymbol{\Sigma}^*) \quad \text{with } \boldsymbol{\Sigma}^* := \mathbf{D}\boldsymbol{\Sigma}\mathbf{D}^\top,$$

with \mathbf{D} denoting the Jacobian of $(z_0, \dots, z_b, \mathbf{h}(z_{b+1}, \dots, z_{b+r}))^\top$ evaluated at $(p_0, \dots, \mu_r)^\top$.



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Application and Implementation

Intermezzo

Crucial question for practice: Possible to compute covariances σ_{ij} of asymptotic $\frac{1}{\sqrt{T}} \sum_{t=1}^T (\mathbf{Z}_t - \mu_{\mathbf{Z}}) \xrightarrow{D} \mathbf{N}(\mathbf{0}, \Sigma)$?

Yes, if h -step-ahead

conditional probabilities $p_{i|j}^{(h)} := P(X_t = i \mid X_{t-h} = j)$ available;
property SYM further simplifies formulae.

For $i, j \in \{0, \dots, b\}$, we have

$$E[Z_{h,i} \cdot Z_{0,j}] - \mu_{\mathbf{Z},i} \mu_{\mathbf{Z},j} = \begin{cases} (\delta_{i,j} - p_i) p_j & \text{if } h = 0, \\ (p_{i|j}^{(h)} - p_i) p_j & \text{if } h > 0, \end{cases}$$

For $i, j \in \{1, \dots, r\}$, we have $\mu_{Z, b+i} = \mu_i$, $\mu_{Z, b+j} = \mu_j$, and

$$E[Z_{h, b+i} \cdot Z_{0, b+j}] = E[X_t^i \cdot X_{t-h}^j] = \begin{cases} \mu_{i+j} & \text{if } h = 0, \\ E[X_t^i \cdot X_{t-h}^j] & \text{if } h > 0. \end{cases}$$

Joint moments $E[X_t^i \cdot X_{t-h}^j]$ often available in practice.

If $r = 1$ (one-parameter H_0 -distribution),
sufficient to compute the autocovariance function.

If no closed-form moment expressions are not available,
then numerical computation from $p_{i|j}^{(h)}$, e. g., by truncating
summation after $M + 1$ summands with M sufficiently large.

For $i = 0, \dots, b$ and $j = 1, \dots, r$,

$$E[Z_{h,b+j} \cdot Z_{0,i}] = \begin{cases} i^j p_i & \text{if } h = 0, \\ E[X_t^j \mid X_{t-h} = i] p_i & \text{if } h > 0. \end{cases}$$

If SYM hold, then

$$E[Z_{h,i} \cdot Z_{0,b+j}] \stackrel{\text{SYM}}{=} E[Z_{h,b+j} \cdot Z_{0,i}].$$

If SYM does not hold, then $E[Z_{h,i} \cdot Z_{0,b+j}] = \sum_{x=0}^{\infty} x^j p_{i|x}^{(h)} p_x$
calculated (numerically) from $p_{i|j}^{(h)}$.

Couple of relevant examples: (. . .)

- **i. i. d. counts:** ✓

- **CLAR(1) model** (Grunwald et al., 2000):

We have $E[Z_{h,b+1} \cdot Z_{0,i}] = (\alpha^h \cdot i + (1 - \alpha^h) \mu) p_i$.

If also SYM holds, then $\sigma_{i,b+1} = (i - \mu) p_i \frac{1+\alpha}{1-\alpha}$.

We also have $\rho(h) = \alpha^h$, so

$$\sigma_{b+1,b+1} = \sigma^2 + 2 \sum_{h=1}^{\infty} \sigma^2 \alpha^h = \sigma^2 \frac{1+\alpha}{1-\alpha}.$$

- **Poisson INAR(1) model** (McKenzie, 1985):

One-parameter ($r = 1$) marginal $p_i = e^{-\mu} \mu^i / i!$, $\hat{\mu} = \bar{X}$;

CLAR(1) model with property SYM.

- **Poisson INAR(1) model** (McKenzie, 1985):

One-parameter ($r = 1$) marginal $p_i = e^{-\mu} \mu^i / i!$, $\hat{\mu} = \bar{X}$;
CLAR(1) model with property SYM.

For $i, j \in \{0, \dots, b\}$,

$$\begin{aligned}\sigma_{ij} &= (\delta_{i,j} - p_i) p_j + 2 p_j \sum_{h=1}^{\infty} (p_{i|j}^{(h)} - p_i) \\ &\approx (\delta_{i,j} - p_i) p_j + 2 p_j \sum_{h=1}^M (p_{i|j}^{(h)} - p_i),\end{aligned}$$

where simple closed-form formula for $p_{i|j}^{(h)}$.

Computationally more efficient to utilize that

$$(X_t, X_{t-h}) \sim \text{BPoi}(\alpha^h \mu; (1 - \alpha^h) \mu, (1 - \alpha^h) \mu).$$

- **Binomial AR(1) model** (McKenzie, 1985):
CLAR(1) model with property SYM (like before),
one-parameter ($r = 1$) marginal $p_i = \binom{n}{i} \pi^i (1 - \pi)^{n-i}$,
moment estimator $\hat{\pi} := \bar{X}/n$, so
Jacobian $\mathbf{D} = \text{diag}(1, \dots, 1, 1/n)$.
 - **Geometric INAR(1) model** (McKenzie, 1985):
CLAR(1) model, but property SYM does not hold!
Numerical approximation for $p_{i|j}^{(h)}$ and $\sigma_{i,b+1}$.
One-parameter ($r = 1$) marginal $p_i = \pi (1 - \pi)^i$,
moment estimator $\hat{\pi} = 1/(1 + \bar{X})$, so
Jacobian $\mathbf{D} = \text{diag}(1, \dots, 1, -\pi^2)$.
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- **Poisson INAR(2) model** (Alzaid & Al-Osh, 1990):

Poisson marginal, property SYM;

all computations like for Poisson INAR(1), but

$$(X_t, X_{t-h}) \sim \text{BPoi}(\rho(h)\mu; (1 - \rho(h))\mu, (1 - \rho(h))\mu),$$

$$E[X_t | X_{t-h}] = \rho(h) X_{t-h} + (1 - \rho(h))\mu,$$

$$\rho(1) = \alpha_1 \text{ and } \rho(h) = \alpha_1 \rho(h-1) + \alpha_2 \rho(h-2) \text{ for } h \geq 2.$$

- **Poisson INMA(q) model** (Weiß, 2008):

non-Markovian but q -dependent.

$$(X_t, X_{t-h}) \sim \text{BPoi}(\rho(h)\mu; (1 - \rho(h))\mu, (1 - \rho(h))\mu),$$

requires μ and $\rho(1), \dots, \rho(q)$.

- **NDARMA(p, q) model** (Jacobs & Lewis, 1983):

Defining $c := 1 + 2 \sum_{h=1}^{\infty} \rho(h)$,

$$\sigma_{ij} = c (\delta_{i,j} - p_i) p_j,$$

$$\sigma_{i,b+j} = c (i^j - \mu_j) p_i,$$

$$\sigma_{b+i,b+j} = c (\mu_{i+j} - \mu_i \mu_j).$$

Corresponds to i. i. d.-case with additional factor c .

- **Hidden-Markov model** (Zucchini & MacDonald, 2009):

Marginal and lagged bivariate probabilities as

$$P(X_t = i) = \mathbf{1}^\top \mathbf{P}(i) \boldsymbol{\pi},$$

$$P(X_t = i, X_{t-h} = j) = \mathbf{1}^\top \mathbf{P}(i) \mathbf{A}^h \mathbf{P}(j) \boldsymbol{\pi}.$$



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Asymptotics

Let's return to asymptotics $\sqrt{T} ((\hat{p}, \hat{\theta}) - (p, \theta))$.

Step 2: derive asymptotics of $\sqrt{T} G(\hat{p}, \theta)$ and $\sqrt{T} G(\hat{p}, \hat{\theta})$.

Let $z = (z_1, z_2)$ with $z_1 \in \mathbb{R}^{b+1}$ and $z_2 \in \mathbb{R}^r$, define

$$g(z_1, z_2) := \text{diag}(\pi_a(z_2)^{-1/2}, \dots, \pi_{b+1}(z_2)^{-1/2}) \mathbf{A}(z_1 - p(z_2))$$

such that $G(\hat{p}, \theta) = g(\hat{p}, \theta)$ and $G(\hat{p}, \hat{\theta}) = g(\hat{p}, \hat{\theta})$.

Delta method requires Jacobian of g .

- In specified-parameter case, reduced Jacobian suffices,

$$\mathbf{J}_g(\mathbf{z}_1) = \left(\frac{\partial}{\partial z_{1,i}} g_k(\mathbf{z}_1, \boldsymbol{\theta}) \right)_{k=a, \dots, b+1, i=0, \dots, b},$$

leading to

$$\sqrt{T} \mathbf{G}(\hat{\mathbf{p}}, \boldsymbol{\theta}) \xrightarrow{D} N\left(\mathbf{0}, \mathbf{D}_{kn} \boldsymbol{\Sigma}^{(p)} \mathbf{D}_{kn}^\top\right)$$

with $\mathbf{D}_{kn} = \text{diag}\left(\boldsymbol{\pi}(\boldsymbol{\theta})^{-1/2}\right) \mathbf{A}$.

- In estimated-parameter case, full Jacobian required.

Denoting Jacobian of $p(z_2)$ by $\mathbf{J}_p(z_2)$, we obtain

$$\sqrt{T} \mathbf{G}(\hat{\mathbf{p}}, \hat{\boldsymbol{\theta}}) \xrightarrow{D} \mathbf{N}\left(\mathbf{0}, \mathbf{D}_{\text{est}} \boldsymbol{\Sigma}^* \mathbf{D}_{\text{est}}^\top\right)$$

with $\mathbf{D}_{\text{est}} = \begin{pmatrix} \mathbf{D}_{\text{kn}}, & -\mathbf{D}_{\text{kn}} \mathbf{J}_p(\boldsymbol{\theta}) \end{pmatrix}$.

Remark: Jacobian \mathbf{J}_p easily computed for

- Poisson marginal via $\frac{\partial}{\partial \mu} p_i(\mu) = p_{i-1}(\mu) - p_i(\mu)$,
- binomial marg. via $\frac{\partial}{\partial \pi} p_{n,i}(\pi) = n (p_{n-1,i-1}(\pi) - p_{n-1,i}(\pi))$,
- geometric marginal via $\frac{\partial}{\partial \pi} p_i(\pi) = \frac{1}{\pi} p_i(\pi) - i p_{i-1}(\pi)$.

Step 3: We apply Theorem 3.1 in Tan (1977), leading to asymptotic quadratic-form distribution for Pearson's GoF test statistic.

- Specified-parameter case:

$$G^2(\hat{\mathbf{p}}, \boldsymbol{\theta}) \xrightarrow{D} \sum_{i=1}^u \lambda_i Z_i^2,$$

where $\lambda_1, \dots, \lambda_u$ non-zero eigenvalues of $\mathbf{D}_{\text{kn}} \boldsymbol{\Sigma}^{(p)} \mathbf{D}_{\text{kn}}^{\top}$.

- Estimated-parameter case:

$$G^2(\hat{\mathbf{p}}, \hat{\boldsymbol{\theta}}) \xrightarrow{D} \sum_{j=1}^v \lambda_j^* Z_j^2,$$

where $\lambda_1^*, \dots, \lambda_v^*$ non-zero eigenvalues of $\mathbf{D}_{\text{est}} \boldsymbol{\Sigma}^* \mathbf{D}_{\text{est}}^{\top}$.



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■ Computations & Simulations ■

Implementation of asymptotics in R,
using `CompQuadForm` package (Duchesne & de Micheaux, 2010)
to evaluate quadratic-form distributions.

Simulations always use 10 000 replications.

Quantiles of Pearson statistic (estimated parameters)
for binomial AR(1) process, asymptotic vs. simulated values,
where latter (*italic*) taken from Kim & Weiß (2015):

n	π	ρ	T	a	b	$q_{0.25}$		$q_{0.50}$		$q_{0.75}$		$q_{0.95}$		$q_{0.99}$	
5	0.4	0.00	70	0	4	1.923	<i>1.914</i>	3.357	<i>3.268</i>	5.385	<i>5.246</i>	9.49	<i>9.28</i>	13.28	<i>13.66</i>
5	0.4	0.50	70	0	4	2.449	<i>2.351</i>	4.292	<i>3.962</i>	6.921	<i>6.293</i>	12.33	<i>11.73</i>	17.44	<i>18.19</i>
22	0.4	0.00	70	5	11	3.483	<i>3.554</i>	5.377	<i>5.418</i>	7.870	<i>7.903</i>	12.62	<i>12.59</i>	16.84	<i>16.65</i>
22	0.4	0.50	70	5	11	3.845	<i>3.911</i>	5.951	<i>6.000</i>	8.744	<i>8.621</i>	14.14	<i>13.78</i>	19.03	<i>18.80</i>

Properties of Pearson statistic (estimated parameters)
 for Poisson INAR(1) process with $\mu = 3$,
 asymptotic vs. simulated values:

α	T	a	b	mean		std. dev.		$q_{0.25}$		$q_{0.50}$		$q_{0.75}$		$q_{0.95}$		$q_{0.99}$	
0.25	200	0	6	6.15	6.13	3.55	3.50	3.54	3.59	5.48	5.45	8.03	7.94	12.90	12.78	17.23	17.34
	500	0	7	7.16	7.14	3.83	3.81	4.35	4.33	6.49	6.46	9.24	9.22	14.39	14.41	18.91	18.73
	1000	0	8	8.17	8.18	4.09	4.08	5.17	5.23	7.49	7.53	10.43	10.36	15.83	15.73	20.52	20.75
0.50	200	0	6	6.89	6.86	4.04	3.96	3.93	4.00	6.11	6.10	9.00	8.93	14.59	14.20	19.68	19.37
	500	0	7	7.98	7.94	4.34	4.33	4.81	4.81	7.20	7.18	10.30	10.26	16.19	15.91	21.48	21.17
	1000	0	8	9.05	8.95	4.61	4.64	5.69	5.59	8.27	8.17	11.56	11.36	17.71	17.64	23.16	23.45
0.75	200	0	6	10.49	10.16	6.68	6.35	5.72	5.74	9.04	8.84	13.65	13.12	23.29	21.88	32.82	31.66
	500	0	7	11.99	11.69	7.12	7.02	6.90	6.84	10.52	10.25	15.44	14.81	25.55	24.64	35.42	35.68
	1000	0	8	13.40	13.32	7.46	7.62	8.06	8.01	11.93	11.80	17.11	16.74	27.55	27.44	37.64	39.53

Properties of Pearson statistic (estimated parameters)
 for geometric INAR(1) process with $\mu = 3$,
 asymptotic vs. simulated values:

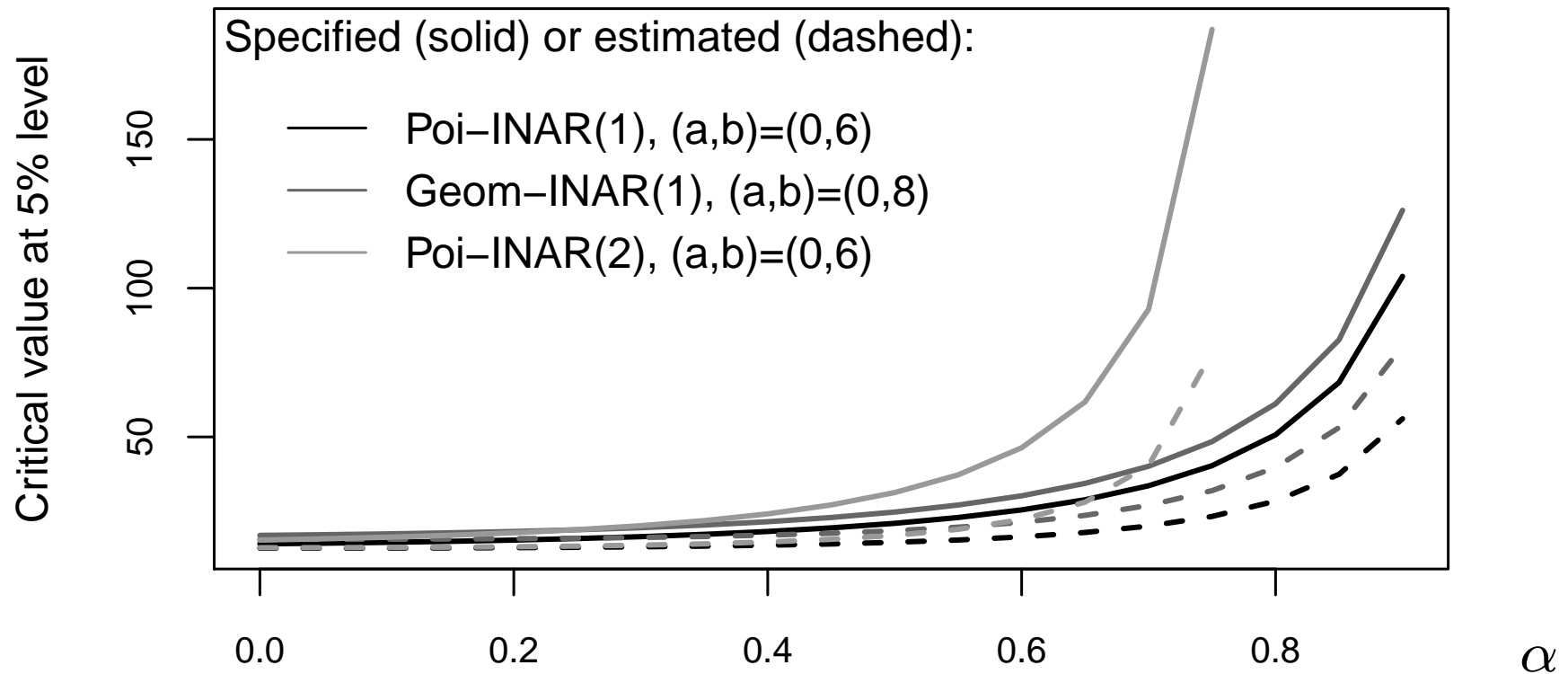
α	T	a	b	mean		std. dev.		$q_{0.25}$		$q_{0.50}$		$q_{0.75}$		$q_{0.95}$		$q_{0.99}$	
0.25	200	0	8	8.25	8.32	4.11	4.14	5.24	5.30	7.57	7.63	10.52	10.58	15.97	16.05	20.73	20.67
	500	0	11	11.21	11.19	4.79	4.78	7.72	7.71	10.53	10.53	13.95	13.95	20.07	19.90	25.26	25.33
	1000	0	13	13.19	13.28	5.19	5.31	9.43	9.42	12.51	12.67	16.22	16.41	22.73	22.92	28.19	28.59
0.50	200	0	8	9.29	9.26	4.88	4.79	5.77	5.77	8.41	8.39	11.83	11.81	18.48	18.09	24.71	24.46
	500	0	11	12.25	12.35	5.48	5.54	8.29	8.38	11.39	11.45	15.25	15.32	22.44	22.84	28.94	29.48
	1000	0	13	14.23	14.34	5.85	5.85	10.02	10.17	13.39	13.51	17.51	17.57	25.02	25.21	31.69	31.70
0.75	200	0	8	14.86	14.67	8.97	8.70	8.59	8.52	12.87	12.87	18.87	18.72	31.96	31.51	45.58	43.51
	500	0	11	18.03	18.09	9.49	9.60	11.39	11.42	16.10	16.04	22.47	22.53	35.99	36.35	49.89	50.67
	1000	0	13	20.09	20.22	9.78	9.91	13.24	13.27	18.20	18.20	24.77	24.99	38.50	39.14	52.50	53.28

Properties of Pearson statistic (estimated parameters)
 for Poisson INAR(2) process with $\mu = 3$,
 asymptotic vs. simulated values:

α_1	α_2	T	a	b	mean		std. dev.		$q_{0.25}$		$q_{0.50}$		$q_{0.75}$		$q_{0.95}$		$q_{0.99}$	
0.25	0.25	200	0	6	6.44	6.35	3.74	3.71	3.70	3.64	5.73	5.68	8.41	8.28	13.56	13.32	18.18	18.17
		500	0	7	7.48	7.43	4.03	4.04	4.53	4.47	6.76	6.71	9.65	9.58	15.09	15.06	19.89	19.79
		1000	0	8	8.50	8.49	4.28	4.34	5.37	5.33	7.79	7.68	10.86	10.84	16.55	16.42	21.52	22.12
0.50	0.25	200	0	6	8.36	8.11	5.25	5.00	4.60	4.58	7.24	7.10	10.86	10.46	18.37	17.61	25.80	24.98
		500	0	7	9.61	9.37	5.61	5.65	5.59	5.49	8.48	8.15	12.36	11.84	20.24	19.60	27.96	29.49
		1000	0	8	10.79	10.68	5.89	5.93	6.57	6.53	9.66	9.59	13.75	13.41	21.91	21.77	29.79	30.66
0.75	0.10	200	0	6	13.60	12.84	9.37	8.91	7.04	6.97	11.35	10.84	17.63	16.29	31.64	28.74	46.20	45.19
		500	0	7	15.44	14.86	9.96	10.01	8.45	8.24	13.15	12.62	19.85	18.69	34.56	32.74	49.67	50.32
		1000	0	8	17.12	16.65	10.39	10.70	9.80	9.47	14.82	14.29	21.85	21.00	37.01	36.05	52.43	53.78

Critical values w.r.t. Poisson or geometric marginal distribution having mean $\mu = 3$, sample size $T = 200$;

INAR(2) process satisfies $\alpha_1 = \alpha, \alpha_2 = 0.2$:



Simulated size of Pearson test (level 5 %) for Poisson INAR(1), Poisson INAR(2) (also if misspecified as Poisson INAR(1)), and geometric INAR(1) process, all having mean $\mu = 3$:

$\alpha =$					misspec. as					
α_1	α_2	T	a	b	Poi-INAR(1)	Poi-INAR(2)	Poi-INAR(1)	a	b	Geom-INAR(1)
0.25	0.25	200	0	6	0.050	0.046	0.058	0	8	0.049
		500	0	7	0.046	0.049	0.062	0	11	0.052
		1000	0	8	0.051	0.047	0.059	0	13	0.051
0.50	0.25	200	0	6	0.049	0.055	0.104	0	8	0.055
		500	0	7	0.045	0.044	0.100	0	11	0.051
		1000	0	8	0.048	0.048	0.110	0	13	0.051
0.75	0.10	200	0	6	0.049	0.076	0.132	0	8	0.078
		500	0	7	0.047	0.057	0.125	0	11	0.058
		1000	0	8	0.047	0.052	0.127	0	13	0.052

Simulated size and power of Pearson test (level 5%)
 for Poisson INAR(1) process (dispersion index $I = 1$)
 and NB-INAR(1) process ($I > 1$), respectively,
 all having mean $\mu = 3$:

α	T	a	b	Rejection rates; $I =$				
				1	1.05	1.10	1.20	1.50
0.25	200	0	6	0.050	0.065	0.094	0.228	0.796
	500	0	7	0.046	0.085	0.174	0.537	0.997
	1000	0	8	0.051	0.120	0.325	0.857	1.000
0.50	200	0	6	0.049	0.060	0.082	0.179	0.695
	500	0	7	0.045	0.082	0.160	0.460	0.987
	1000	0	8	0.048	0.118	0.288	0.769	1.000
0.75	200	0	6	0.049	0.052	0.064	0.121	0.458
	500	0	7	0.047	0.065	0.104	0.286	0.878
	1000	0	8	0.047	0.090	0.189	0.529	0.995

- Distribution of Pearson's GoF test statistic, if applied to count time series, asymptotically approximated by quadratic-form distribution.
- Distribution can be explicitly computed for variety of practically relevant count process models.
- Covers both null model being fully specified, and where parameters have to be estimated.
- Simulations: asymptotic approximation works rather well, test successfully applied to uncover model violations.

Thank You for Your Interest!



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