

Detection of Abrupt Changes in Count Data Time Series: Cumulative Sum Derivations for INARCH(1) Models



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All references mentioned in this talk
correspond to the references in this article.



INARCH(1) Model for Serially Dependent Counts

Motivation & Properties



INARCH(1) Model for Dependent Counts



Process monitoring often concerned with **attributes data**.

We consider process $\{X_t : t = 1, 2, 3, \dots\}$ of **counts**, i. e., where each X_t has range $\mathbb{N}_0 = \{0, 1, \dots\}$.

Examples:

- number of nonconformities in production unit,
- number of service errors in given time interval.

Such data often exhibit serial dependence, e. g., Knoth & Schmid (2004): “typical pattern of data” in medical, environmental, or financial statistics.



INARCH(1) Model for Dependent Counts



Variables data \rightarrow **Gaussian AR(1) model:**

$$Z_{t+1} = \rho \cdot Z_t + \epsilon_t, \quad \text{where } (\epsilon_t) \text{ i.i.d. } N(\mu_\epsilon, \sigma_\epsilon^2).$$

Not applicable to counts data.

Possible discrete-valued counterpart:

INARCH(1) model, where

$$X_t \Big|_{X_{t-1}, X_{t-2}, \dots} \sim \text{Pois}(\beta + \alpha \cdot X_{t-1}),$$

i. e., Markov chain (X_t) with transition probabilities

$$P(X_t = i \mid X_{t-1} = j) = \exp(-\beta - \alpha \cdot j) \cdot \frac{(\beta + \alpha \cdot j)^i}{i!}.$$



INARCH(1) model: $X_t \sim \text{Pois}(\beta + \alpha \cdot X_{t-1})$.

Properties:

- Stationary and ergodic Markov chain
(Ferland et al., 2006; Zhu and Wang, 2009);
- all moments exist (Ferland et al., 2006), in particular
- $\mu = \frac{\beta}{1 - \alpha}$, $\sigma^2 = \frac{\beta}{(1 - \alpha)(1 - \alpha^2)}$ (overdispersion);
- AR(1)-like autocorrelation function $\rho(k) = \alpha^k$.



INARCH(1) model: $X_t \sim \text{Pois}(\beta + \alpha \cdot X_{t-1})$.

Parameter estimation:

- Method of moments via $\bar{X}_T, \hat{\rho}(1)$.
- Conditional maximum likelihood via

$$\begin{aligned} L(\beta, \alpha) &:= P(X_T = x_T, \dots, X_2 = x_2 \mid X_1 = x_1) \\ &\sim e^{-(T-1)\beta} \cdot e^{-\alpha \cdot \sum_{t=2}^T x_{t-1}} \cdot \prod_{t=2}^T (\beta + \alpha \cdot x_{t-1})^{x_t}. \end{aligned}$$

Note: Simple expression for log-likelihood ratio,

$$\begin{aligned} \ell R(\beta_0, \alpha_0, \beta_1, \alpha_1) &:= \ln \frac{L(\beta_1, \alpha_1)}{L(\beta_0, \alpha_0)} \\ &= \sum_{t=2}^T \left(-(\beta_1 - \beta_0) - (\alpha_1 - \alpha_0)x_{t-1} + x_t \cdot \ln\left(\frac{\beta_1 + \alpha_1 x_{t-1}}{\beta_0 + \alpha_0 x_{t-1}}\right) \right). \end{aligned}$$



INARCH(1) Model for Dependent Counts



INARCH(1) model: $X_t \sim \text{Pois}(\beta + \alpha \cdot X_{t-1})$.

Interpretation:

X_t = *total* number of “events” at time t
= events that newly start at time t
plus events that have started earlier.

also included in X_{t-1} ,
“survivors” from time $t - 1$

$\alpha \approx$ mean rate of survivors from previous period,

$\beta \approx$ mean number of new events starting at each time.



INARCH(1) Model for Dependent Counts



INARCH(1) model: $X_t \sim \text{Pois}(\beta + \alpha \cdot X_{t-1})$.

Real-data example: (Weiß, 2010)

Monthly strike counts, U.S. Bureau of Labor Statistics,
Jan. 1994 to Dec. 2002 (108 observations).

x_t = total number of work stoppages

leading to ≥ 1000 workers being idle in effect in period t .

Mean 4.94 but variance 7.92 \Rightarrow overdispersed.

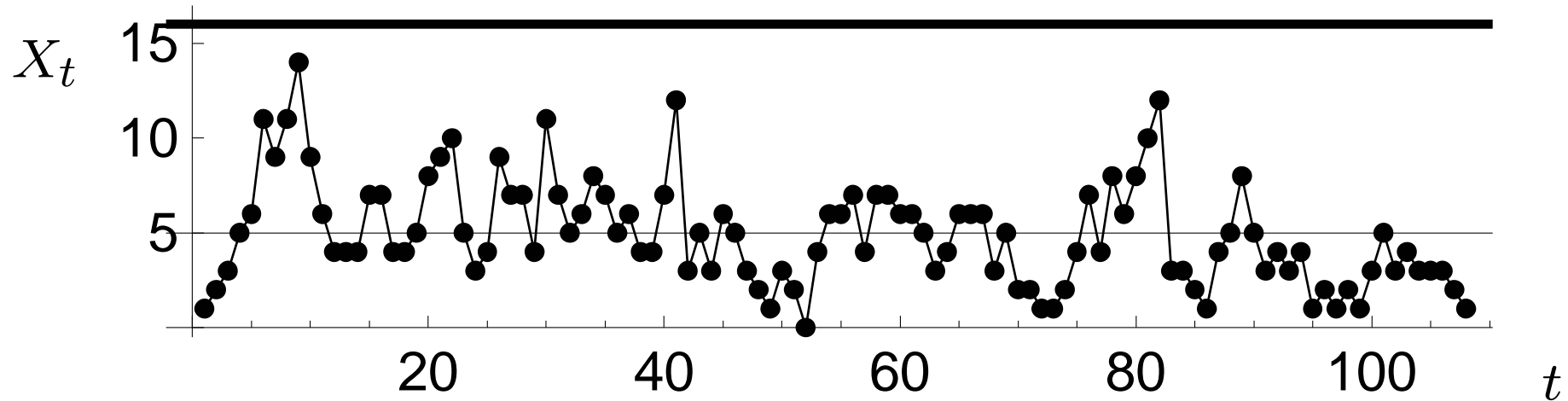
AR(1)-like autocorrelation structure with $\hat{\rho}(1) \approx 0.57$.



INARCH(1) Model for Dependent Counts



c chart of **strike count data**:



ML estimates $\hat{\alpha} \approx 0.64$ and $\hat{\beta} \approx 1.81$,

i. e., model mean ≈ 5.0 and model variance ≈ 8.5 .

Interpretation: mean number of new strikes is 1.81,
about 64 % of strikes in a month continue in next month.



CUSUM Monitoring of an INARCH(1) Process

Approaches



Situation:

Process $(X_t)_{\mathbb{Z}}$, monitoring starts at time $t = 1$.

Before change point $\tau \in \mathbb{Z}$:

$\dots, X_{\tau-2}, X_{\tau-1}$ follow *in-control model*,

i. e., INARCH(1) with $\alpha = \alpha_0, \beta = \beta_0$.

For $t \geq \tau$: parameters shifted to *out-of-control* values α_1, β_1 .

Benchmark chart: conventional (upper-sided) CUSUM

$$C_0 = 0, \quad C_t = \max(0; X_t - k + C_{t-1}) \quad \text{for } t = 1, 2, \dots,$$

where upper limit h adjusted for serial dependence and overdispersion. (Weiß & Testik, 2009)



CUSUM Charts based on Likelihood Ratio:

Log-likelihood ratio $\ell R(\beta_0, \alpha_0, \beta_1, \alpha_1) = \sum_{t=1}^T \ell R_t$, where

$$\ell R_t := -(\beta_1 - \beta_0) - (\alpha_1 - \alpha_0)x_{t-1} + x_t \cdot \ln\left(\frac{\beta_1 + \alpha_1 x_{t-1}}{\beta_0 + \alpha_0 x_{t-1}}\right),$$

with $\ell R_1 := 0$ (see above).

Given a certain out-of-control parametrization (β_1, α_1) , we can derive related CUSUM chart for this purpose.

Plotting always starts with time $t = 2$.

Approach exemplified for three cases: ...



Case 1: $\beta_1 = (1 + \delta)\beta_0$ and $\alpha_1 = (1 + \delta)\alpha_0$, i. e., simultaneous change by same relative amount.

Then

$$\ell R_t = -\delta \cdot (\beta_0 + \alpha_0 x_{t-1}) + \ln(1 + \delta) \cdot x_t$$

leads to CUSUM

$$C_t^{(1)} = \max(0; C_{t-1}^{(1)} - k \cdot (\beta_0 + \alpha_0 X_{t-1}) + \ln(1 + k) \cdot X_t).$$

Note: For $\delta \rightarrow 0$, we obtain residuals CUSUM,

$$\ell R_t \approx \delta \cdot (x_t - \beta_0 - \alpha_0 x_{t-1}).$$



Case 2: $\beta_1 = (1 + \delta)\beta_0$ and $\alpha_1 = \alpha_0$, i. e.,
change only in β .

Then

$$\ell R_t = -\delta\beta_0 + x_t \cdot \ln\left(1 + \frac{\delta\beta_0}{\beta_0 + \alpha_0 x_{t-1}}\right)$$

leads to CUSUM

$$C_t^{(2)} = \max\left(0; C_{t-1}^{(2)} - k\beta_0 + X_t \cdot \ln\left(1 + \frac{k\beta_0}{\beta_0 + \alpha_0 X_{t-1}}\right)\right).$$



Case 3: $\beta_1 = \beta_0$ and $\alpha_1 = (1 + \delta)\alpha_0$, i. e.,
change only in α .

Then

$$\ell R_t = -\delta\alpha_0 x_{t-1} + x_t \cdot \ln\left(1 + \frac{\delta\alpha_0 x_{t-1}}{\beta_0 + \alpha_0 x_{t-1}}\right)$$

leads to CUSUM

$$C_t^{(3)} = \max\left(0; C_{t-1}^{(3)} - k\alpha_0 \cdot X_{t-1} + X_t \cdot \ln\left(1 + \frac{k\alpha_0 X_{t-1}}{\beta_0 + \alpha_0 X_{t-1}}\right)\right).$$



CUSUM Monitoring of an INARCH(1) Process

Performance



Performance metrics:

zero-state ARL, i. e., $ARL^{(1)} := E[L \mid \tau = 1]$,

steady-state ARL, i. e., $ARL^{(\infty)} := \lim_{\tau \rightarrow \infty} ARL^{(\tau)}$,

where $ARL^{(\tau)} := E[L - \tau + 1 \mid L \geq \tau, \tau]$ for $\tau \geq 1$.

Chart design always such that $ARL_0^{(1)} \approx 370$.

Out-of-control behavior in terms of $ARL^{(1)}$ and $ARL^{(\infty)}$.

Computation of ARLs:

For benchmark CUSUM exactly via MC approach,

for LR-CUSUMs via simulations using $\widehat{ARL}^{(200)}$

(1 mio. replications; details in Appendix of article).



Performance evaluation: Detailed tables in article.

In-control par.: $\beta_0 = 2$, $\alpha_0 = 0.6$ and $\beta_0 = 3.5$, $\alpha_0 = 0.3$.

Considered δ values 0, 0.025, 0.05, 0.1, 0.25, 0.5, 1, 1.5.

Chart design for LR-CUSUMs with $k = 0.1, 0.25, 0.5, 1.0$.

Besides above out-of-control cases (used for design),
also situation considered, where

β, α shifted by different relative amounts (\rightarrow robustness).



Performance evaluation: Detailed tables in article.

Main findings:

- Benchmark CUSUM is good choice if relative shifts $\geq 50\%$ in α or β to be detected (advantage: simple, exact ARL computation).
- Otherwise: LR-CUSUM chart recommended, with k close to relevant shift level δ .
Note: Choice of k has large effect on performance.
- Appropriate choice of k with regard to α more important than with regard to β .



- **Work in progress:**

Poisson INAR(1) model: complex likelihood, but effective process monitoring by considering specialized residuals?

- **Further research issues:**

Monitoring of higher order or non-stationary INGARCH processes.

Extend INARCH(1) model and related charts to situation of varying sample size.

Thank You for Your Interest!



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