

Diagnosing Overdispersion in Count Data Time Series



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This talk is based on the articles

Schweer, S., Weiß, C.H. (2014).

*Compound Poisson INAR(1) processes:
stochastic properties and testing for overdispersion.*

Comp. Stat. Data Anal. **77**, 267–284.

Weiß, C.H., Schweer, S. (2014).

Detecting overdispersion in INARCH(1) processes.

Work in progress.

Further details and references are provided by this article.



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INAR(1) Model for Time Series of Counts

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Motivation & Properties

Popular for **real-valued** stationary processes:

ARMA(p,q) model. Let $(\epsilon_t)_{\mathbb{Z}}$ white noise, then

$$X_t = \alpha_1 \cdot X_{t-1} + \dots + \alpha_p \cdot X_{t-p} + \epsilon_t + \beta_1 \cdot \epsilon_{t-1} + \dots + \beta_q \cdot \epsilon_{t-q},$$

where $\alpha_1, \dots, \alpha_p, \beta_1, \dots, \beta_q \in \mathbb{R}$ suitably chosen.

Autocorrelation via **Yule-Walker equations:**

$$\rho_X(k) = \sum_{j=1}^p \alpha_j \cdot \rho_X(|k-j|) + \frac{\sigma_\epsilon^2}{\sigma_X^2} \cdot \sum_{i=0}^{q-k} \beta_{i+k} \cdot a_i + \delta_{k0} \cdot \frac{\sigma_\epsilon^2}{\sigma_X^2}.$$

Example: AR(1) model $X_t = \alpha \cdot X_{t-1} + \epsilon_t$ with $\rho_X(k) = \alpha^k$.

Not applicable to count data processes: generally, $\alpha \cdot X \notin \mathbb{N}_0$.

Several approaches in literature of
how to avoid the “multiplication problem”.

In first part of this talk, we consider models based on
binomial thinning operator (Steutel & van Harn, 1979):

$$\alpha \circ X := \sum_{i=1}^X Y_i, \quad \text{where } Y_i \text{ are i.i.d. Bin}(1, \alpha),$$

i. e., $\alpha \circ X \sim \text{Bin}(X, \alpha)$ and has range $\{0, \dots, X\}$.

(\approx number of “survivors” from population of size X)

Let $(\epsilon_t)_{\mathbb{Z}}$ be i.i.d. with range $\mathbb{N}_0 = \{0, 1, \dots\}$,
denote $\mathbb{E}[\epsilon_t] = \mu_\epsilon$, $\text{Var}[\epsilon_t] = \sigma_\epsilon^2$. Let $\alpha \in (0; 1)$.

$(X_t)_{\mathbb{Z}}$ referred to as **INAR(1) process** if

$$X_t = \alpha \circ X_{t-1} + \epsilon_t,$$

plus appropri. independence assumptions. (McKenzie, 1985)

Properties: (also see lecture)

Homogeneous Markov chain with

$$\mathbb{P}(X_t = k \mid X_{t-1} = l) = \sum_{j=0}^{\min\{k,l\}} \binom{l}{j} \alpha^j (1 - \alpha)^{l-j} \cdot \mathbb{P}(\epsilon_t = k - j).$$

If INAR(1) process stationary (see below), then

$$\text{pgf}_X(z) = \text{pgf}_X(1 - \alpha + \alpha z) \cdot \text{pgf}_\epsilon(z).$$

In particular, if $\mu_\epsilon, \sigma_\epsilon < \infty$, we have

$$\mu_X = \frac{\mu_\epsilon}{1 - \alpha}, \quad \sigma_X^2 = \mu_X \cdot \frac{\frac{\sigma_\epsilon^2}{\mu_\epsilon} + \alpha}{1 + \alpha}.$$

(Note: X_t equidispersed iff ϵ_t equidispersed.)

Autocorrelation function: $\rho_X(k) = \alpha^k$, i. e., AR(1)-type.

For further properties and references, see Weiß (2008).

Most popular instance of INAR(1) family:

Poisson INAR(1) model,
$$X_t = \alpha \circ X_{t-1} + \epsilon_t.$$

Here, innovations $(\epsilon_t)_{\mathbb{Z}}$ i.i.d. $\text{Poi}(\lambda)$, such that $\mu_\epsilon = \sigma_\epsilon^2 = \lambda$.

Stationary marginal distribution:

also Poisson distribution, $\text{Poi}(\frac{\lambda}{1-\alpha})$, because:

additivity of Poisson distribution, and

Poisson distribution **invariant to binomial thinning**:

If $X \sim \text{Poi}(\mu)$, then $\alpha \circ X \sim \text{Poi}(\alpha \cdot \mu)$.

Poisson INAR(1) has **equidispersed** marginals.

Modifications to get **overdispersed** marginals:

- modify thinning operation (Weiß, 2008), or
- modify distribution of innovations, e. g.,
as in Jung et al. (2005), Pedeli & Karlis (2011):
negative binomially (NB) distributed ϵ_t 's.

In the following, we more generally consider
compound Poisson (CP) distributed innovations.



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Compound Poisson INAR(1) Processes

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Definition & Properties

Y_1, Y_2, \dots i.i.d. with range $\mathbb{N} = \{1, 2, \dots\}$,

denote pgf as $H(z)$ (**compounding distribution**).

Let $N \sim \text{Poi}(\lambda)$, independent of Y_1, Y_2, \dots

$\epsilon := Y_1 + \dots + Y_N$ **compound Poisson distributed:**

$\epsilon \sim \text{CP}(\lambda, H)$.

Then $\text{pgf}_\epsilon(z) = \exp(\lambda(H(z) - 1))$. (Feller, 1968)

More precisely:

$\epsilon \sim \text{CP}_\nu(\lambda, H)$ if $H(z) = h_1 z + \dots + h_\nu z^\nu$ with $h_\nu > 0$,

$\epsilon \sim \text{CP}_\infty(\lambda, H)$ if Y_i have infinite range.

Some examples:

- $CP_1(\lambda, H) = \text{Poi}(\lambda)$.
- CP_ν with $\nu < \infty$ and $h_x = 1/\nu$ for $x = 1, \dots, \nu$:
Poisson distribution of order ν , abbr. $\text{Poi}_\nu(\lambda)$.
- NB(n, π)-distribution: CP_∞ with $\lambda := -n \ln \pi$ and

$$H(z) = \frac{\ln(1 - (1 - \pi)z)}{\ln \pi} = \sum_{k=1}^{\infty} \frac{(1 - \pi)^k}{-k \ln \pi} z^k.$$

Important properties: (also see lecture)

- $\kappa_{\epsilon, r} = \lambda \cdot \mu_{Y, r}$ (Aki, 1985)

\Rightarrow

ϵ equidispersed iff $\nu = 1$,

ϵ overdispersed iff $\nu > 1$.

- If X_1, X_2 independent with $X_i \sim \text{CP}_\nu(\lambda_i, H_i)$ (common ν), then $X_1 + X_2 \sim \text{CP}_\nu(\lambda, H)$ -distributed.
- If $X \sim \text{CP}_\nu(\lambda, H)$, then $\alpha \circ X \sim \text{CP}_\nu(\mu, G)$.

INAR(1) process $(X_t)_{t \in \mathbb{Z}}$ referred to as

CPINAR(1) process

if innovations $(\epsilon_t)_{\mathbb{Z}}$ i.i.d. $CP_\nu(\lambda, H)$ (possibly $\nu = \infty$).

$\nu = 1$: Poisson INAR(1) model.

NB-innovations: Jung et al. (2005), Pedeli & Karlis (2011).

We showed (also see lecture):

If $H'(1) < \infty$, then unique **stationary** marginal distribution of $(X_t)_{t \in \mathbb{Z}}$ is $CP_\nu(\mu, G)$, where

$$\mu(G(z) - 1) = \lambda \sum_{i=0}^{\infty} (H(1 - \alpha^i + \alpha^i z) - 1).$$

Preliminary summary:

Stationary CPINAR(1) process with $CP_\nu(\lambda, H)$ -innovations has $CP_\nu(\mu, G)$ -observations (same ν), i. e.,

$(X_t)_{t \in \mathbb{Z}}$ is **equidispersed iff** $\nu = 1$,

$(X_t)_{t \in \mathbb{Z}}$ is **overdispersed iff** $\nu > 1$.

Aim: Develop test to distinguish between

- null hypothesis of equidispersion ($\nu = 1$), and
- alternative hypothesis of overdispersion ($\nu > 1$).

Index of dispersion: $I_X := \frac{\sigma_X^2}{\mu_X}, \quad \hat{I}_X := \frac{S_X^2}{\bar{X}}.$



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Compound Poisson INAR(1) Processes

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Testing for Overdispersion

Index of dispersion: $I_X := \frac{\sigma_X^2}{\mu_X}, \quad \hat{I}_X := \frac{S_X^2}{\bar{X}}.$

Theorem:

For CPINAR(1) process $(X_t)_{\mathbb{Z}}$ with $H'(1) < \infty$,

$$\sqrt{T} \cdot (\hat{I}_X - I_X) \xrightarrow{\mathcal{D}} N(0, \sigma^2) \quad \text{as } T \rightarrow \infty,$$

$$\begin{aligned} \sigma^2 = & \frac{1 + \alpha}{1 - \alpha} (\mu_X - \sigma_X^2) \left(\frac{\bar{\mu}_{X,3}}{\mu_X^3} - \frac{\sigma_X^4}{\mu_X^4} \right) \\ & + \frac{1 + \alpha^2}{1 - \alpha^2} \left(\frac{\bar{\mu}_{X,4}}{\mu_X^2} - \frac{\bar{\mu}_{X,3}}{\mu_X^3} (\mu_X + \sigma_X^2) + \frac{\sigma_X^4}{\mu_X^3} (1 - \mu_X) \right). \end{aligned}$$

Design of **test for overdispersion**:

H_0 : $(X_t)_{t \in \mathbb{Z}}$ follows *Poisson INAR(1)* model
with parameters (λ, α) .

In this case, we have

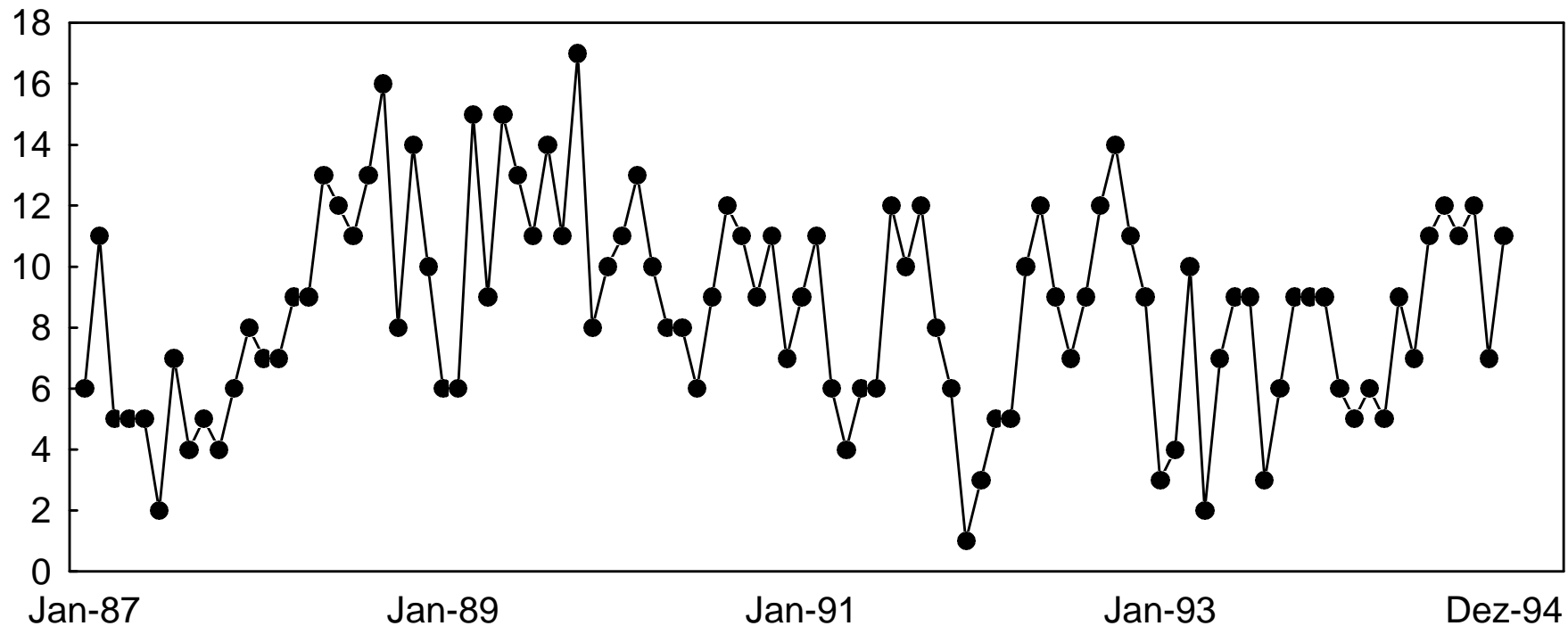
$$\sqrt{T} \cdot (\hat{I}_X - 1) \xrightarrow{\mathcal{D}} N\left(0, 2 \frac{1 + \alpha^2}{1 - \alpha^2}\right) \quad \text{as } T \longrightarrow \infty.$$

\Rightarrow critical value

$$1 + z_{1-\psi} \cdot \sqrt{\frac{2}{T} \frac{1 + \alpha^2}{1 - \alpha^2}},$$

where $z_{1-\psi}$: $(1 - \psi)$ -quantile of $N(0, 1)$ -distribution.

Example: Monthly claims counts (1987 to 1994):
burn related injuries in heavy manufacturing industry.
Source: Freeland (1998).



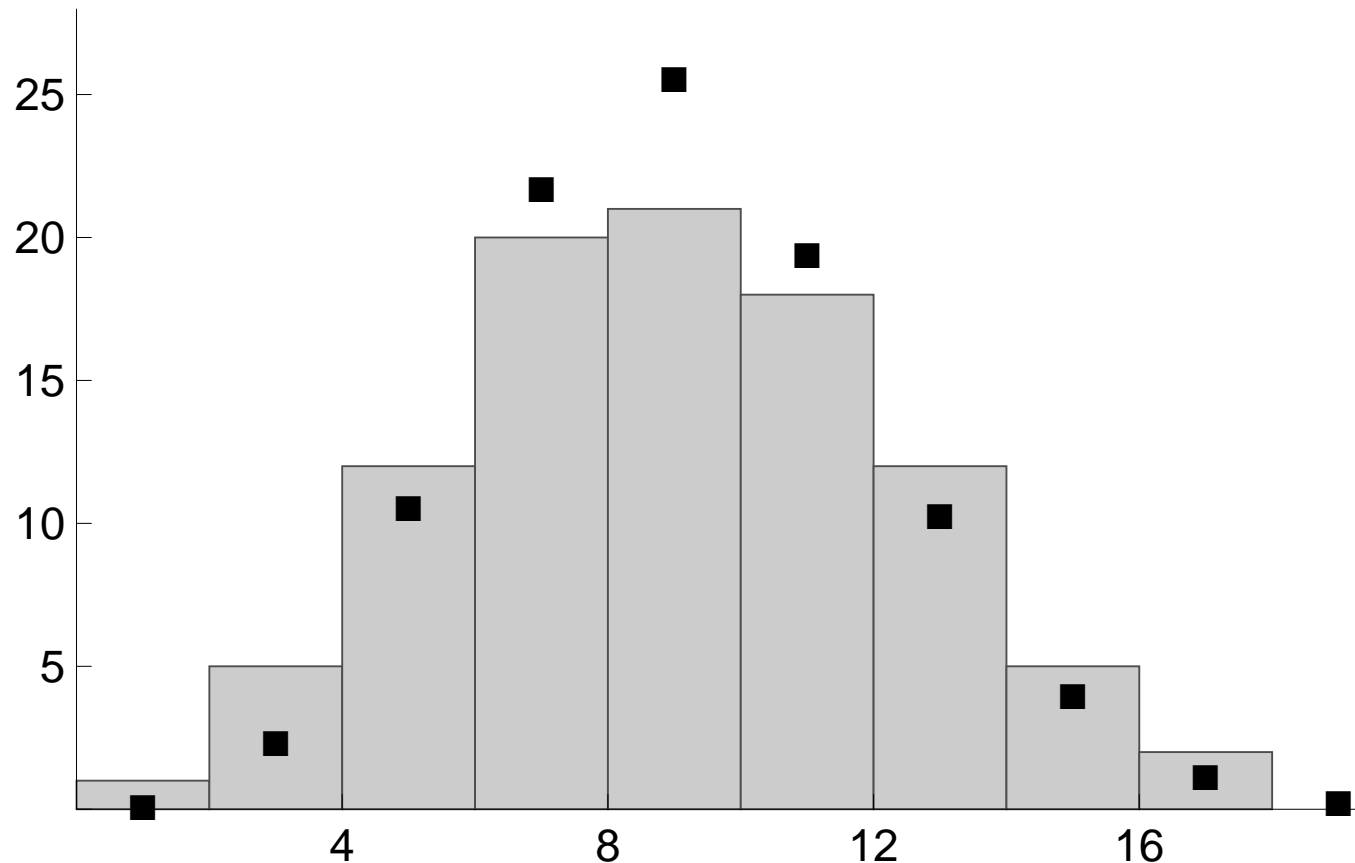
Example (continued): Freeland's claims counts data.

Length $T = 96$, $\bar{x} \approx 8.604$, $s_x^2 \approx 11.24$

$\Rightarrow \hat{I}_y \approx 1.306$, i. e., about 31 % of empirical overdispersion.

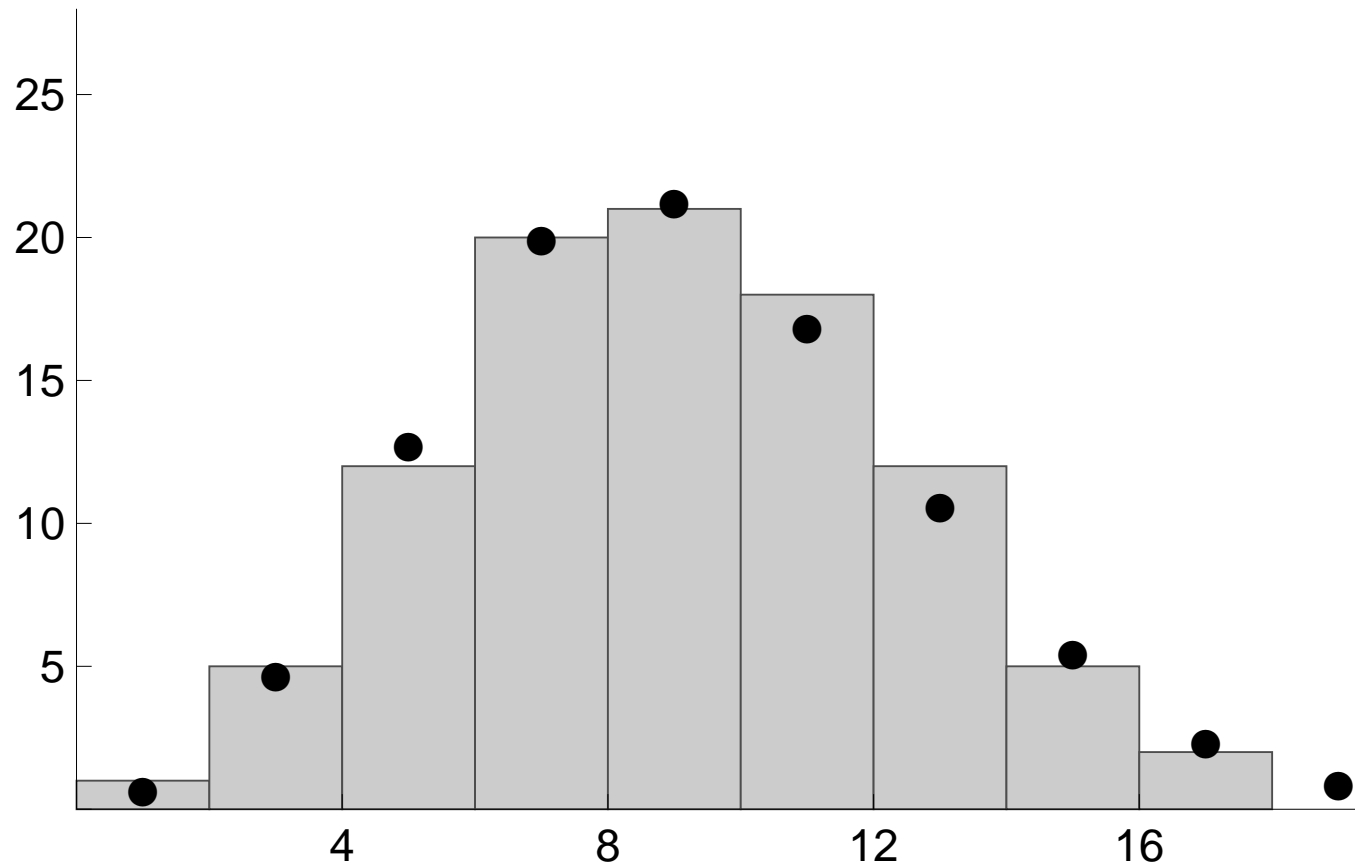
However, plugging-in $\hat{\rho}(1) \approx 0.452$ instead of α ,
critical value 1.292 (significance level $\psi = 0.05$),
i. e., quite narrow decision.

Example (continued): Freeland's claims counts data.



Histogram with fitted Poi-marginal distribution.

Example (continued): Freeland's claims counts data.



Histogram with fitted Poi_2 -marginal distribution.

Our above result

$$\sqrt{T} \cdot (\hat{I}_X - I_X) \xrightarrow{\mathcal{D}} N(0, \sigma^2) \quad \text{as } T \rightarrow \infty,$$

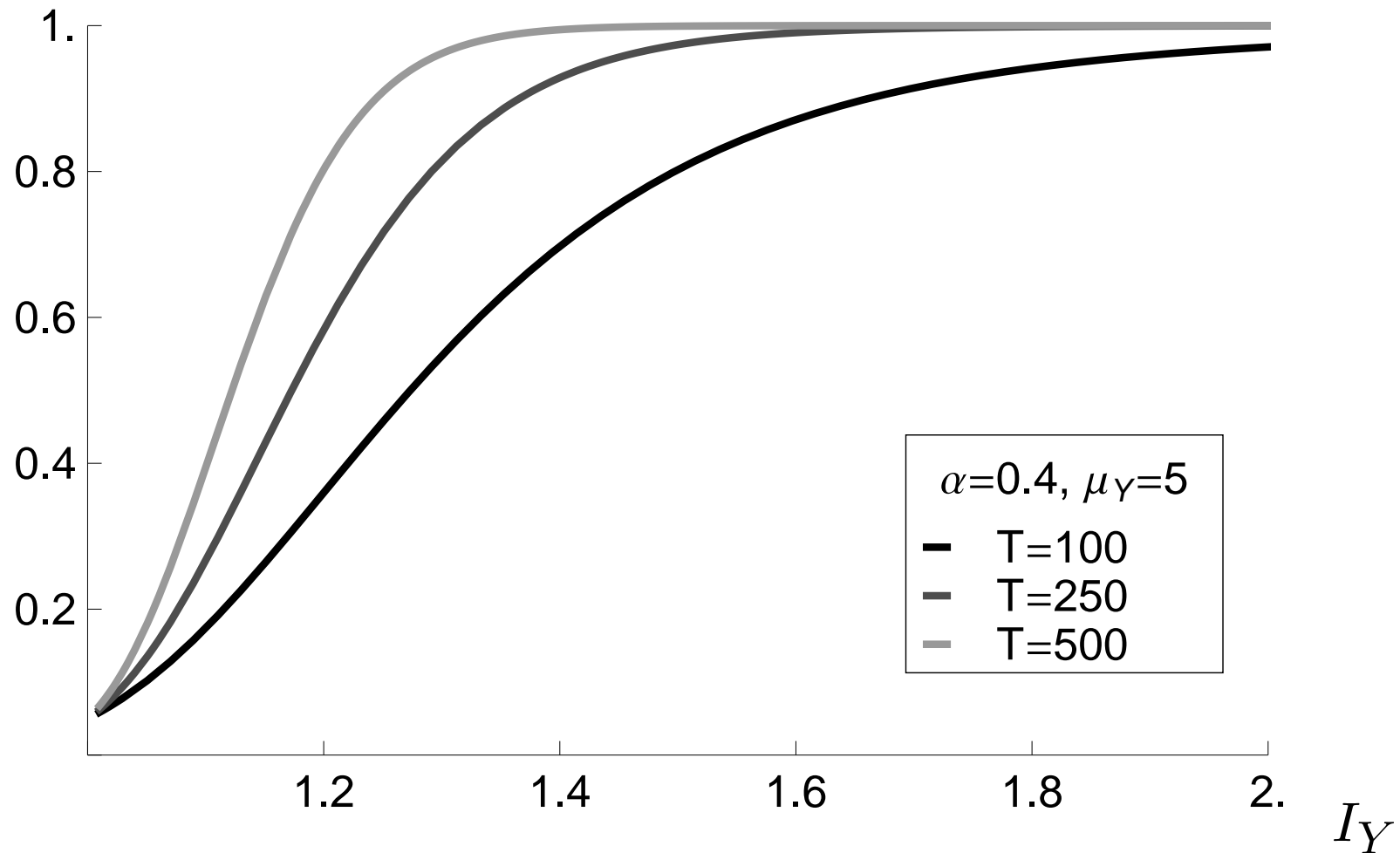
$$\begin{aligned} \sigma^2 = & \frac{1 + \alpha}{1 - \alpha} (\mu_X - \sigma_X^2) \left(\frac{\bar{\mu}_{X,3}}{\mu_X^3} - \frac{\sigma_X^4}{\mu_X^4} \right) \\ & + \frac{1 + \alpha^2}{1 - \alpha^2} \left(\frac{\bar{\mu}_{X,4}}{\mu_X^2} - \frac{\bar{\mu}_{X,3}}{\mu_X^3} (\mu_X + \sigma_X^2) + \frac{\sigma_X^4}{\mu_X^3} (1 - \mu_X) \right), \end{aligned}$$

also applicable to overdispersed alternative!

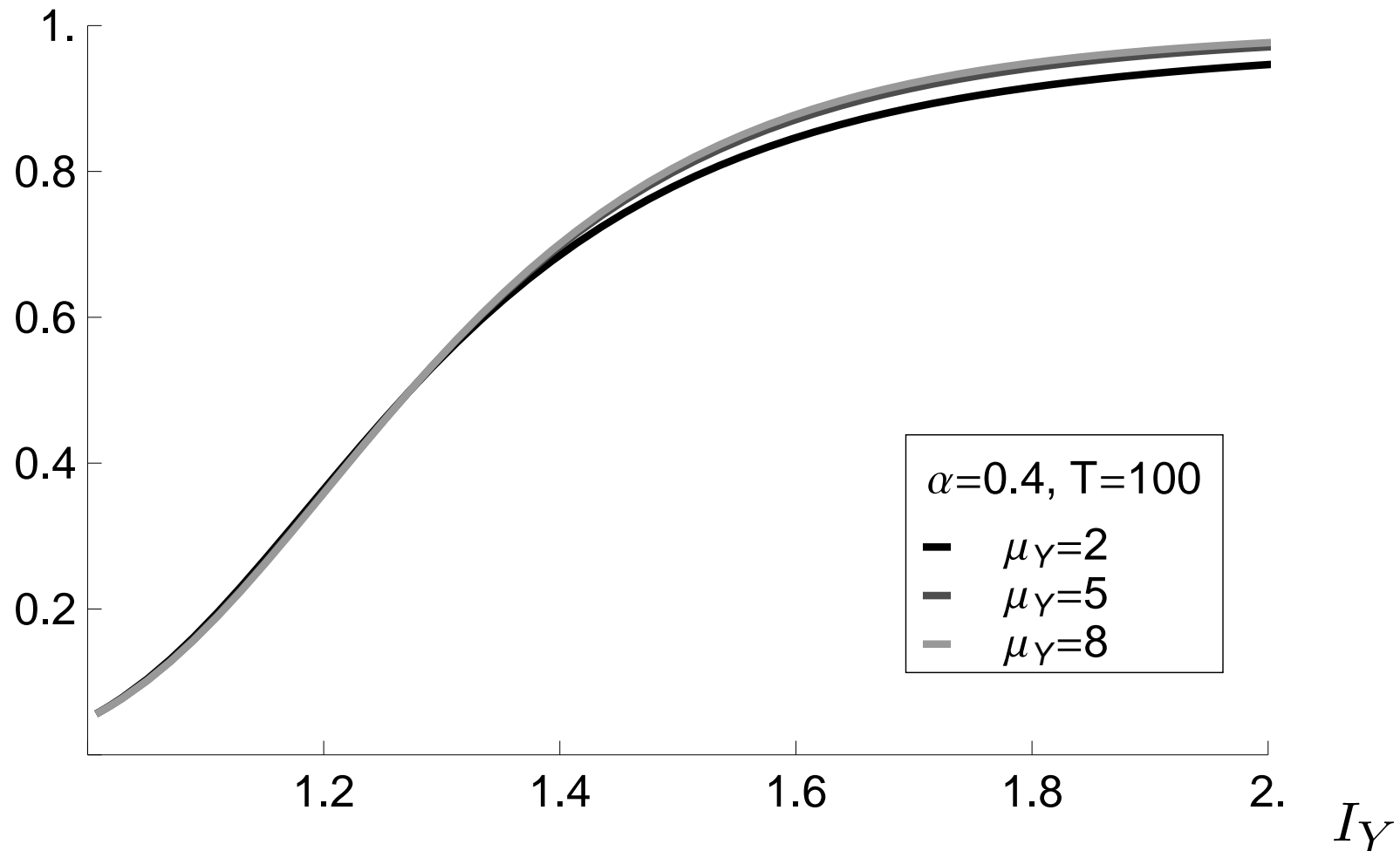
⇒ **Power analysis**, e. g., w.r.t. NB(n, π)-innovations:

n controls mean, π overdispersion, α autocorrelation.

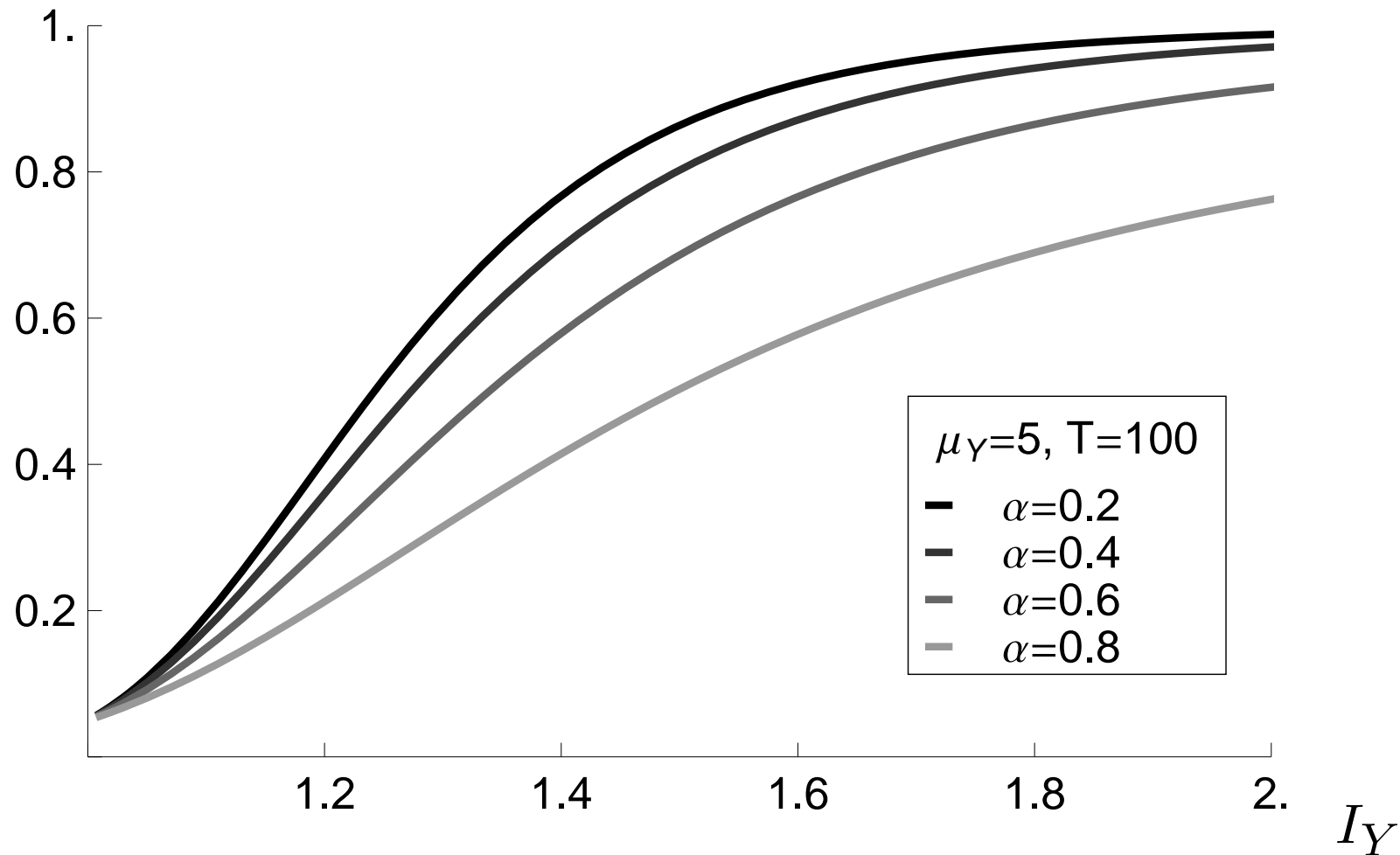
Power analysis w.r.t. $NB(n, \pi)$ -innovations:



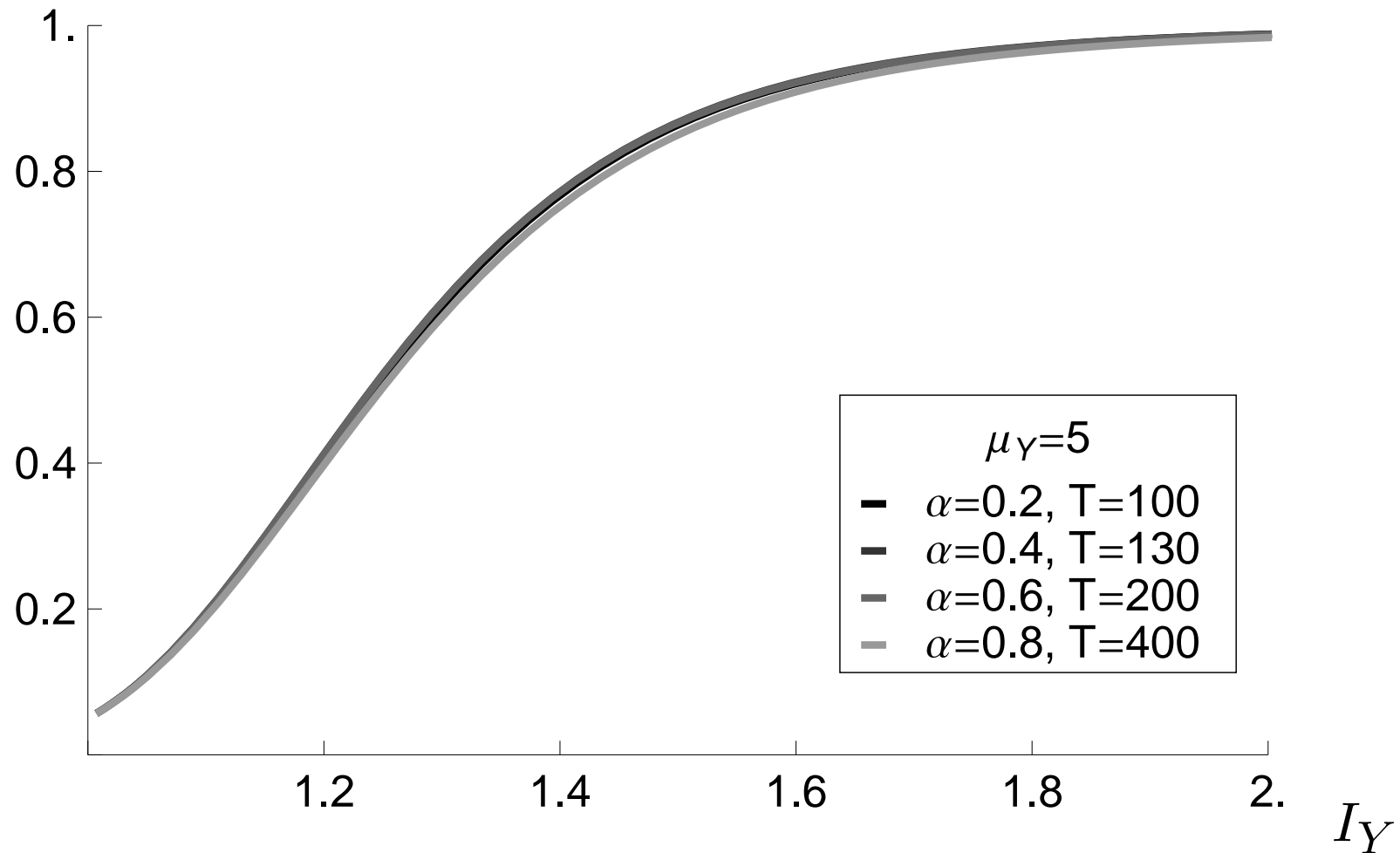
Power analysis w.r.t. $NB(n, \pi)$ -innovations:



Power analysis w.r.t. $NB(n, \pi)$ -innovations:



Power analysis w.r.t. $NB(n, \pi)$ -innovations:



Finite-sample properties:

Simulated Poi-INAR(1) with $(\alpha, \lambda) = (0.40, 5.1)$,

i. e., $\mu_Y = 8.5$ and $I_Y = 1$,

and significance level $\psi = 0.05$ (100,000 repl.):

empir. and asympt. properties of \hat{I}_Y ; empir. rejection rates.

T	mean	s.d.	s.d. _a	skew.	$\hat{q}_{0.05}$	$q_{0.05,a}$	$\hat{q}_{0.95}$	$q_{0.95,a}$	r.r. _{α}	r.r. _a
100	0.977	0.162	0.166	0.421	0.731	0.727	1.262	1.273	0.044	0.050
250	0.991	0.104	0.105	0.265	0.828	0.827	1.169	1.173	0.047	0.050
500	0.995	0.074	0.074	0.191	0.878	0.878	1.120	1.122	0.047	0.050
1000	0.998	0.052	0.053	0.143	0.914	0.914	1.086	1.086	0.049	0.050

Generally rather good approximation,

but visible negative bias for small T .

Based on second-order Taylor expansion,
following **bias-corrected** approximation for mean of \hat{I}
in case of Poisson INAR(1) model:

$$E[\hat{I}] \approx 1 - \frac{1}{T} \frac{1 + \alpha}{1 - \alpha}.$$

Successfully corrects the negative bias for large α and small T .

⇒ **Improved critical value**

$$1 - \frac{1}{T} \frac{1 + \alpha}{1 - \alpha} + z_{1-\psi} \cdot \sqrt{\frac{2}{T} \frac{1 + \alpha^2}{1 - \alpha^2}},$$

where $z_{1-\psi}$: $(1 - \psi)$ -quantile of $N(0, 1)$ -distribution.



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INARCH(1) Model for Time Series of Counts

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Motivation & Properties

Another popular model for

AR(1)-like counts with overdispersion:

two-parametric (Poisson) **INARCH(1) model**,

part of INGARCH family (Heinen, 2003; Ferland et al., 2006),

where “multiplication problem” solved by

applying ARMA recursion to conditional means.

INARCH(1) model:

$$X_t \mid X_{t-1}, X_{t-2}, \dots \sim \text{Poi}(\beta + \alpha \cdot X_{t-1}),$$

where $\beta > 0$ and $0 < \alpha < 1$.

Properties: (also see lecture)

Homogeneous Markov chain with

$$\mathbb{P}(X_t = k \mid X_{t-1} = l) = \exp(-\beta - \alpha \cdot l) \cdot \frac{(\beta + \alpha \cdot l)^k}{k!}.$$

If INARCH(1) process stationary, then

$$\mu = \frac{\beta}{1 - \alpha} \quad \text{and} \quad \sigma^2 = \frac{\beta}{(1 - \alpha)(1 - \alpha^2)} > \mu.$$

Autocorrelation function: $\rho(k) = \alpha^k$, i. e., AR(1)-type.

(Degree of overdispersion depends on autocorrelation level.)



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Index of Dispersion for INARCH(1) Processes

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“Work in Progress”

Theorem:

For stationary INARCH(1) process $(X_t)_{\mathbb{Z}}$,
empirical index of dispersion satisfies

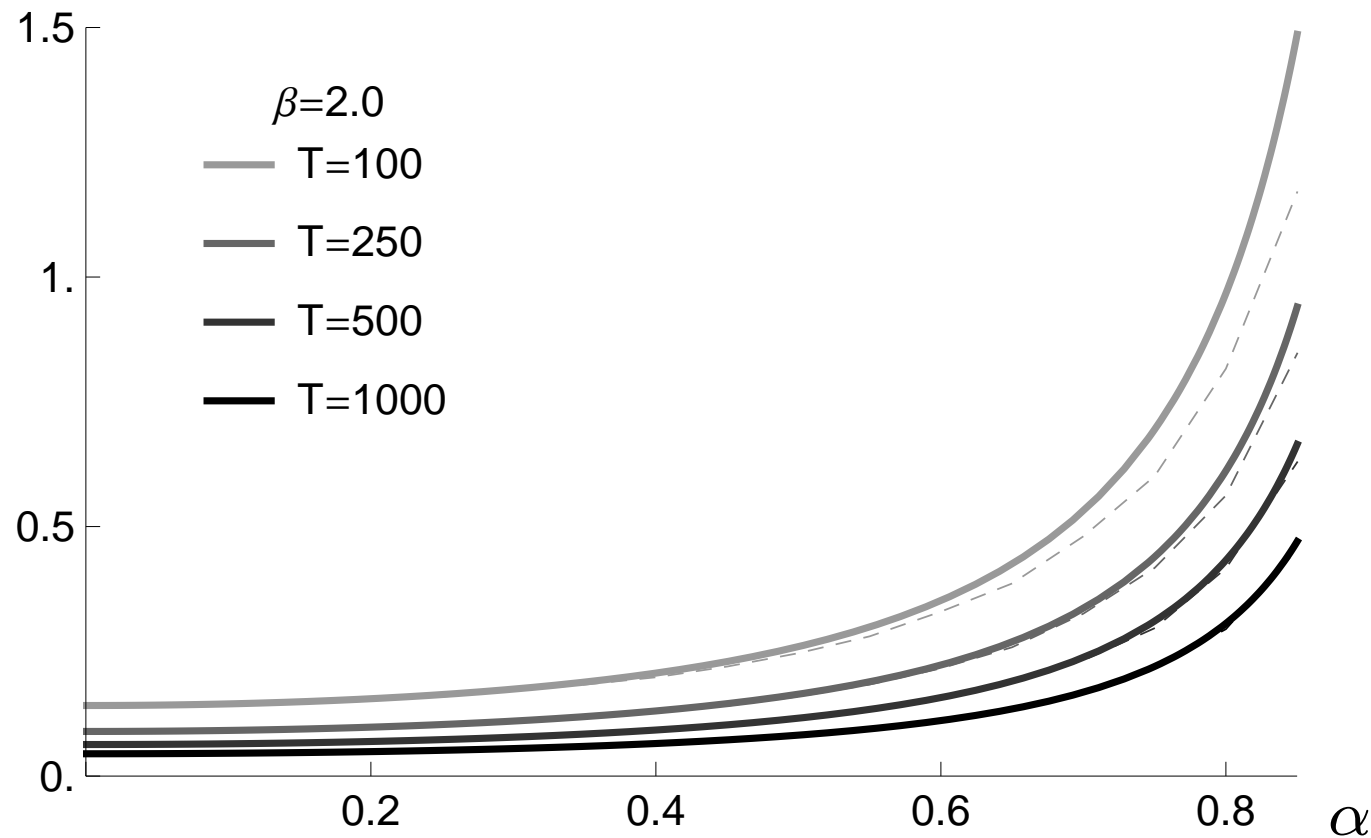
$$\sqrt{T} \left(\hat{I} - \frac{1}{1 - \alpha^2} \right) \xrightarrow{\mathcal{D}} N(0, \sigma_I^2),$$

where

$$\sigma_I^2 = \frac{1}{\mu} \cdot \frac{2\alpha^2(1 + 2\alpha + 3\alpha^3)}{(1 - \alpha^2)^3(1 - \alpha^3)} + \frac{2(1 + \alpha^2)}{(1 - \alpha^2)^3}.$$

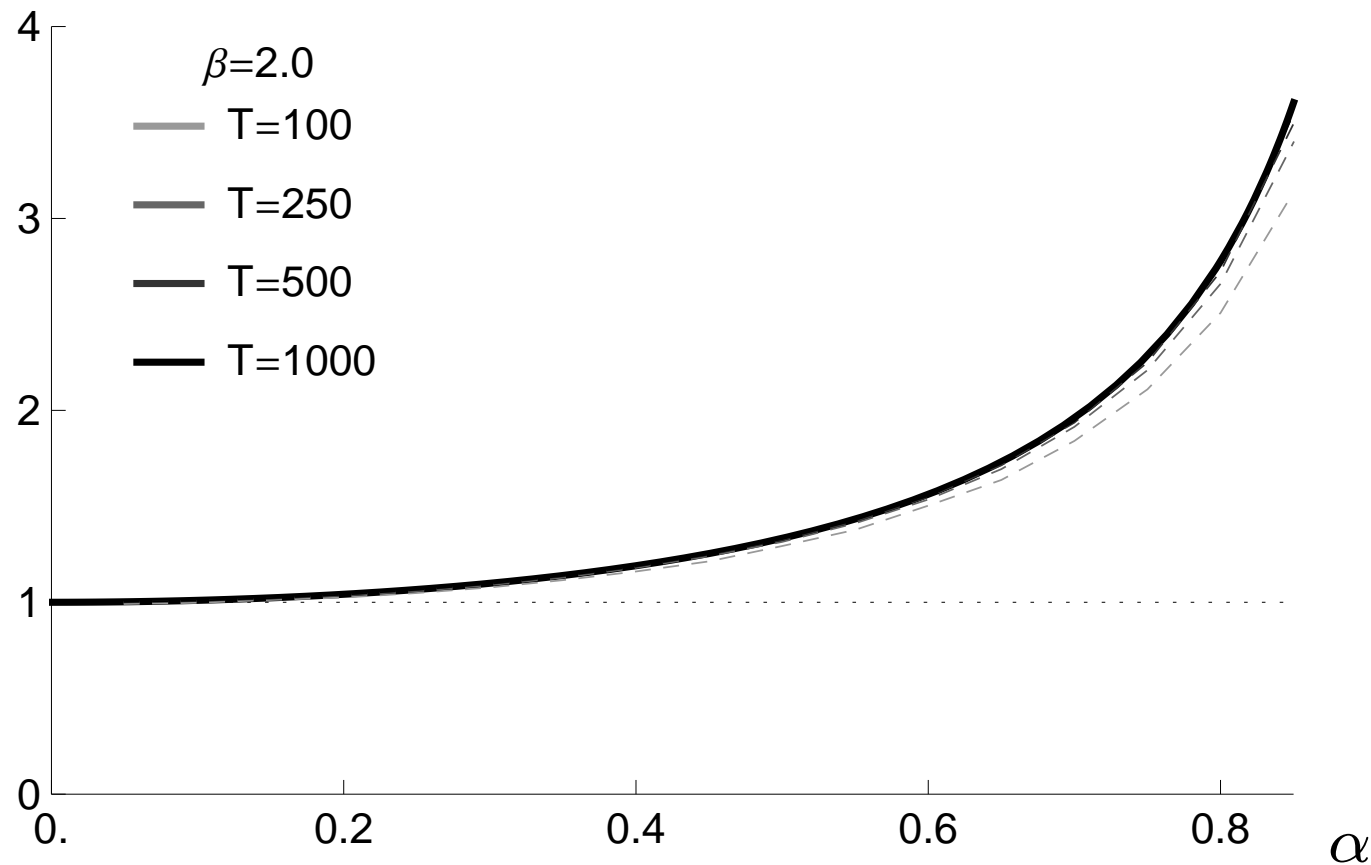
Finite-sample performance: (10,000 replications)

standard deviations of \hat{I} against α ,



Finite-sample performance: (10,000 replications)

means of \hat{I} against α ,



Based on second-order Taylor expansion,
 following **bias-corrected** approximation for mean of \hat{I}
 in case of INARCH(1) model:

$$E[\hat{I}] \approx \frac{1}{1 - \alpha^2} - \frac{1}{T} \cdot \left(\frac{1}{(1 - \alpha)^2} + \frac{2}{\beta} \cdot \frac{\alpha^2}{(1 - \alpha^2)^2} \right).$$

Successfully corrects the negative bias for large α and small T :

α	T $\frac{1}{1-\alpha^2}$	100		250		500		1000	
		b.c.	sim.	b.c.	sim.	b.c.	sim.	b.c.	sim.
0.2	1.042	1.026	1.025	1.035	1.036	1.038	1.038	1.040	1.040
0.4	1.190	1.160	1.160	1.178	1.180	1.184	1.185	1.187	1.187
0.6	1.563	1.491	1.504	1.534	1.536	1.548	1.549	1.555	1.554
0.8	2.778	2.478	2.508	2.658	2.659	2.718	2.723	2.748	2.747

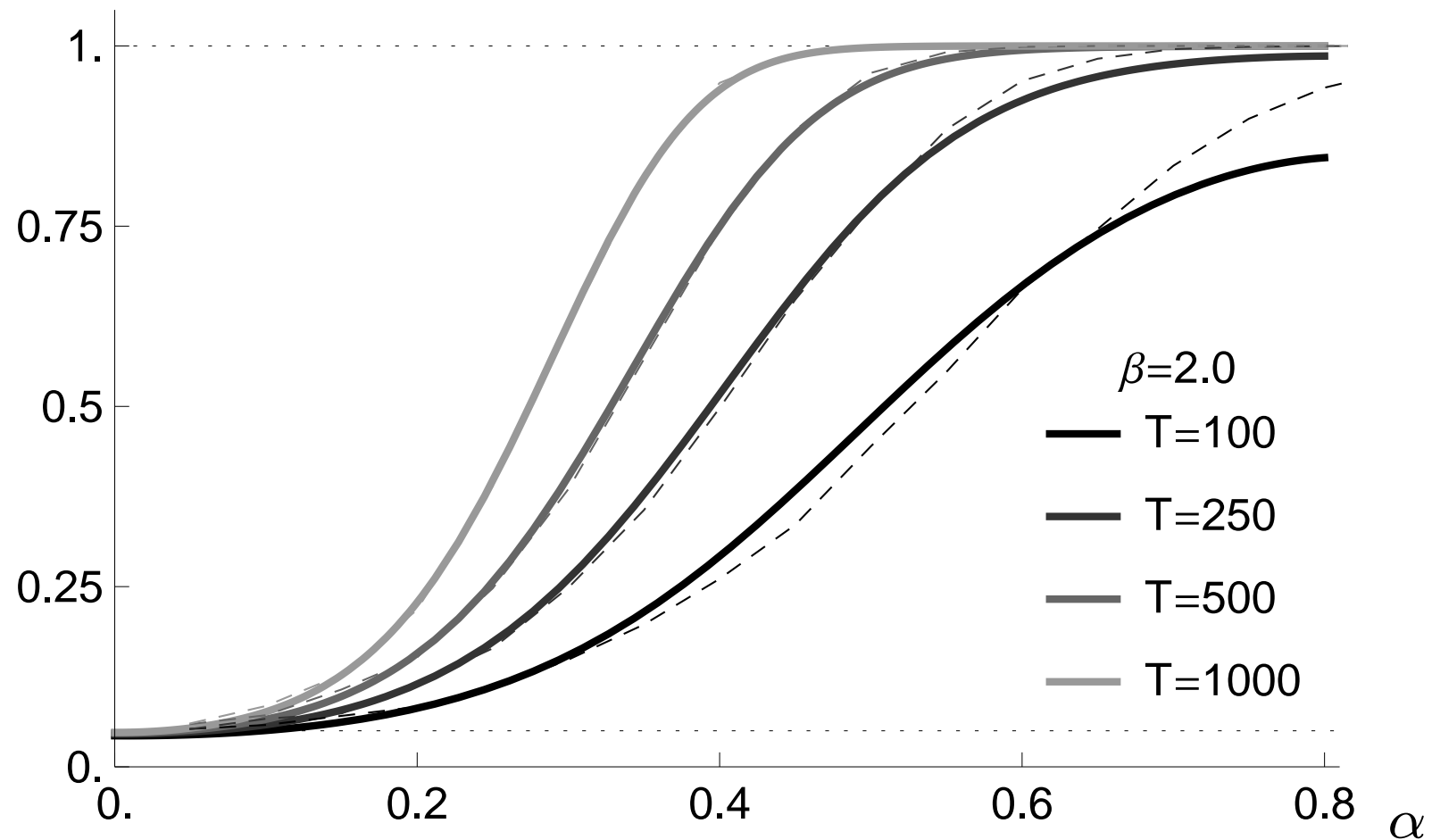
1st application:

H_0 : Poisson INAR(1) model with α and $\mu_\epsilon = \beta$,

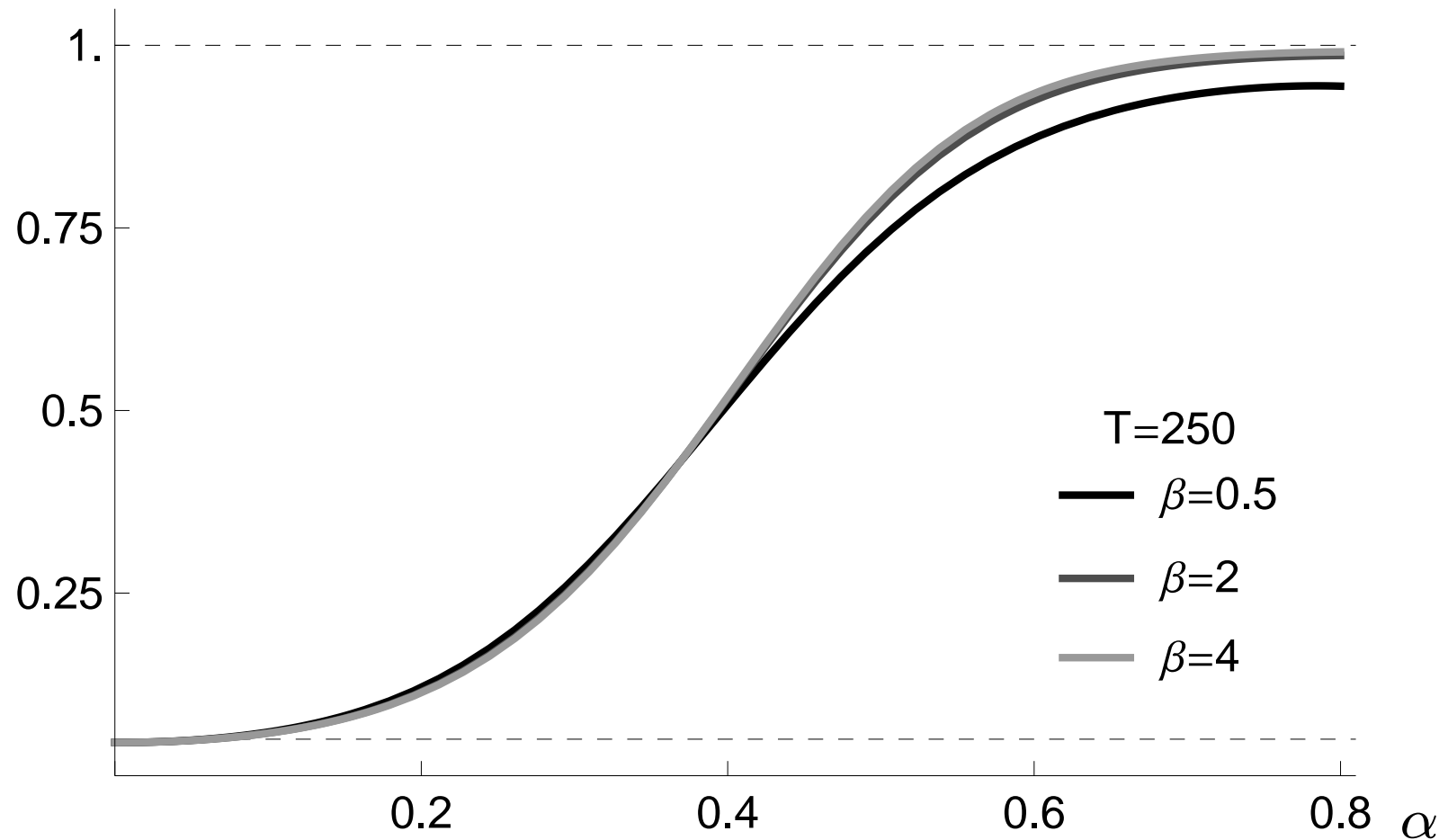
H_1 : INARCH(1) model with α and β ,

power of \hat{I} test in detecting INARCH(1) model?

Power analysis w.r.t. INARCH(1) model:



Power analysis w.r.t. INARCH(1) model:





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INARCH(1) Processes with Conditional Overdispersion

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“Work in Progress”

Dispersed INARCH models (DINARCH) by Xu et al. (2012):

$$\mathbb{E}[X_t \mid X_{t-1}, X_{t-2}, \dots] = \beta + \alpha \cdot X_{t-1},$$

$$\text{Var}[X_t \mid X_{t-1}, X_{t-2}, \dots] = \theta(\beta + \alpha \cdot X_{t-1}).$$

Unconditional mean and variance:

$$\mu = \frac{\beta}{1 - \alpha} \quad \text{and} \quad \sigma^2 = \frac{\theta}{1 - \alpha^2} \cdot \frac{\beta}{1 - \alpha},$$

i. e., θ controls degree of dispersion independently of α .

NB-DINARCH(1) model:

$$X_t \mid X_{t-1}, X_{t-2}, \dots \sim \text{NB} \left(\frac{\beta + \alpha \cdot X_{t-1}}{\theta - 1}, \frac{1}{\theta} \right) \quad \text{with } \theta > 1.$$

2nd application:

H_0 : INARCH(1) model with α and β ,

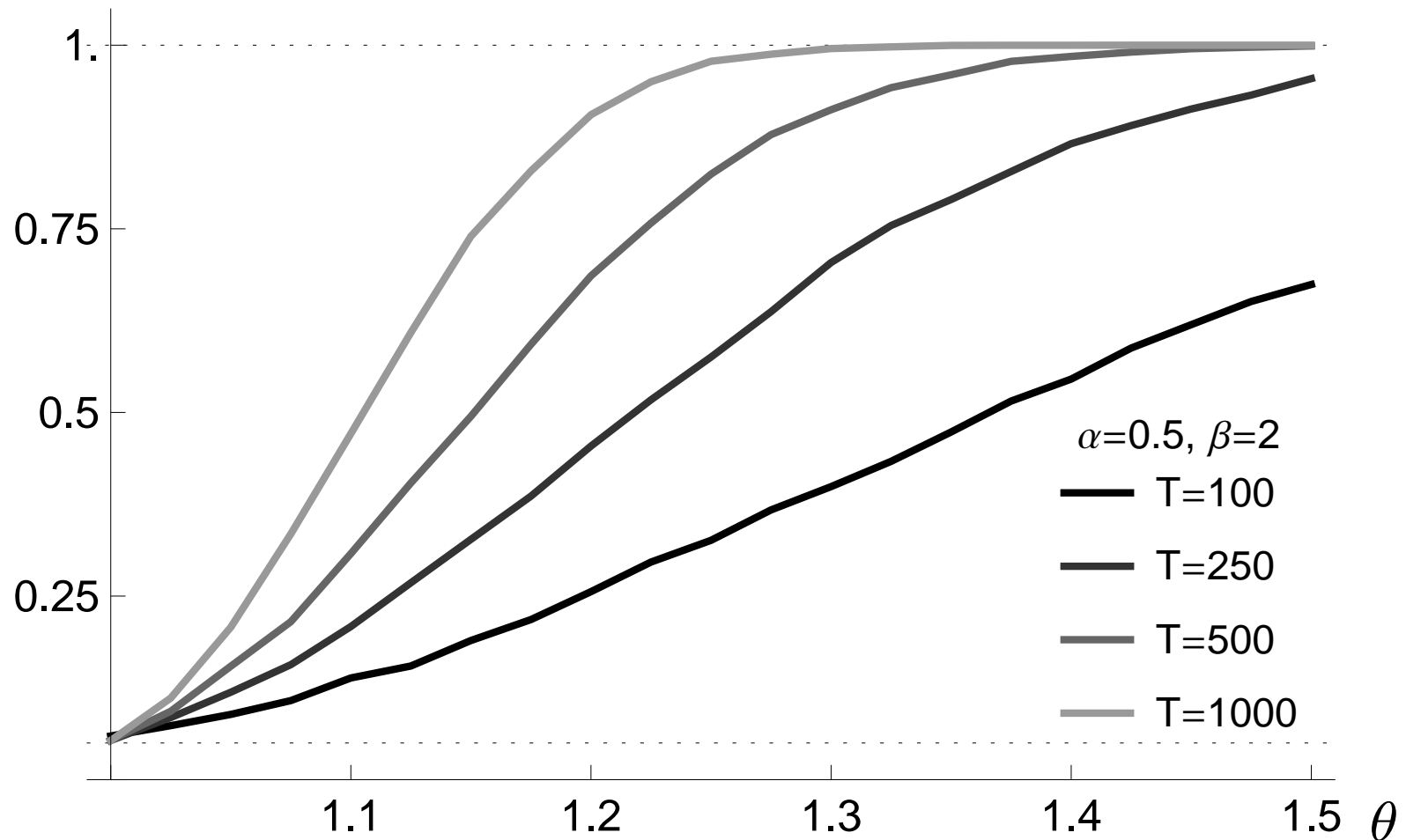
H_1 : NB-DINARCH(1) model with $\theta > 1$.

\hat{I} -test adapted for INARCH(1) leads to **critical value**

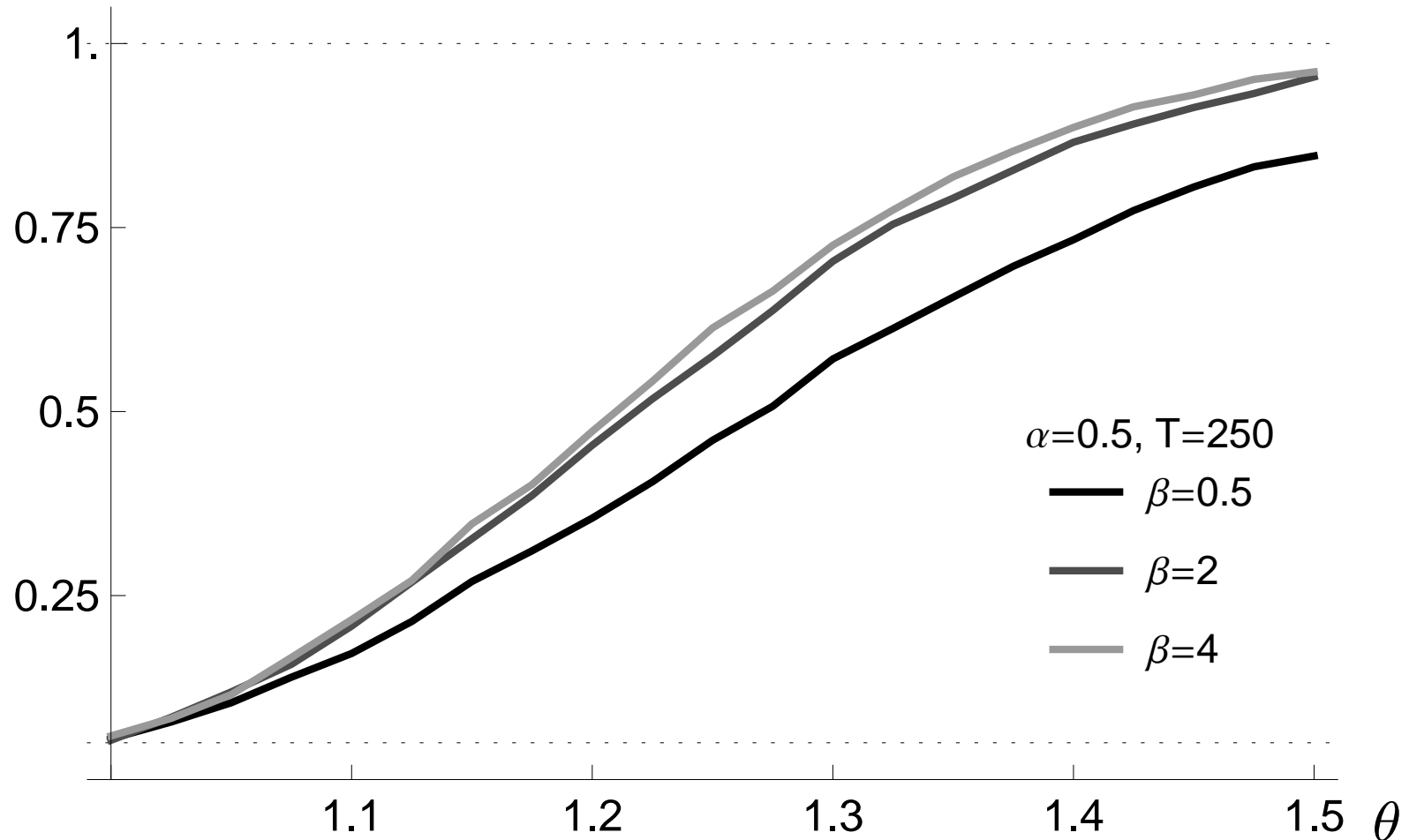
$$\frac{1}{1 - \alpha^2} - \frac{1}{T} \cdot \left(\frac{1}{(1 - \alpha)^2} + \frac{2}{\beta} \cdot \frac{\alpha^2}{(1 - \alpha^2)^2} \right) \\ + z_{1-\psi} \cdot \sqrt{\frac{1}{T} \left(\frac{1}{\mu} \cdot \frac{2\alpha^2(1 + 2\alpha + 3\alpha^3)}{(1 - \alpha^2)^3(1 - \alpha^3)} + \frac{2(1 + \alpha^2)}{(1 - \alpha^2)^3} \right)}.$$

Power of \hat{I} test in detecting NB-INARCH(1) model?

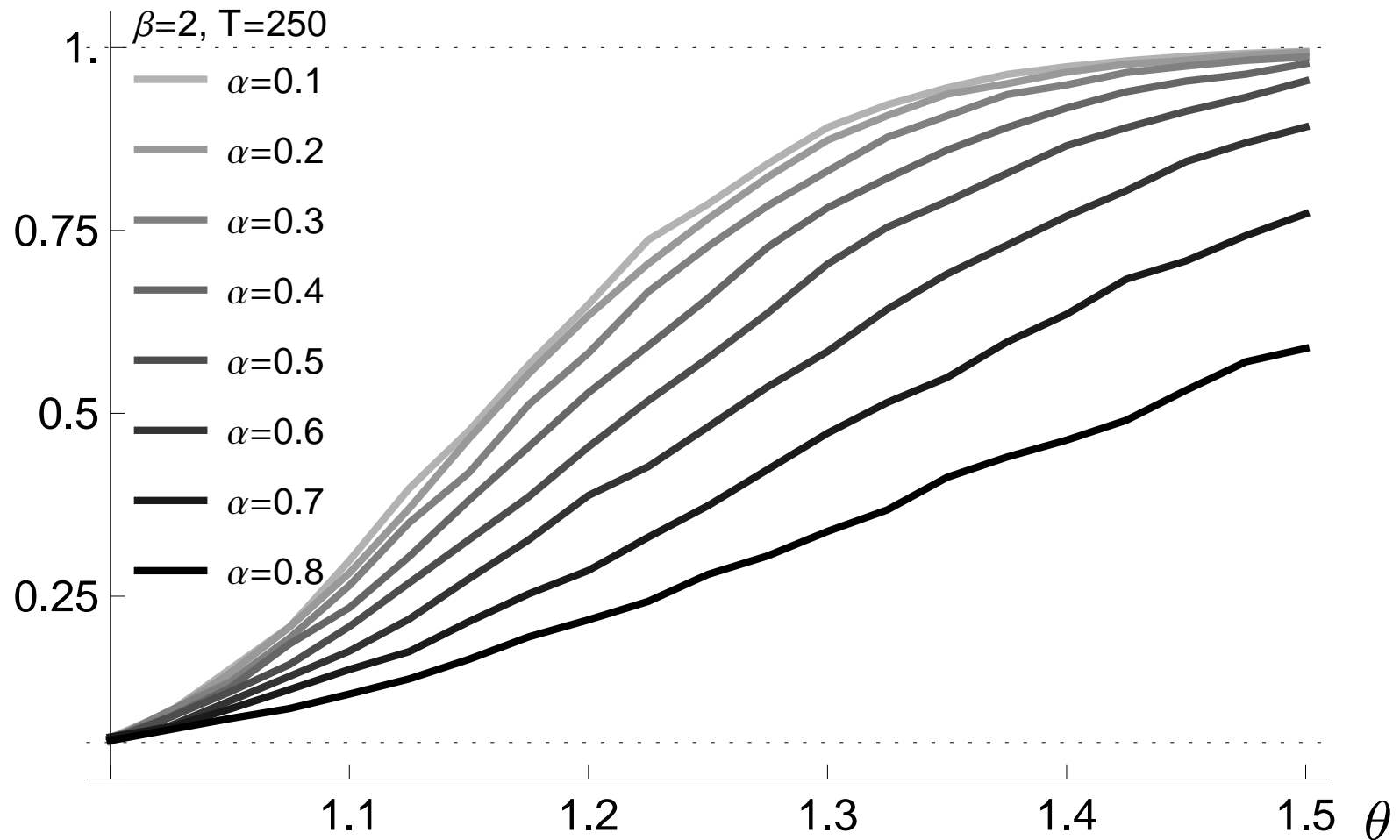
Power analysis w.r.t. NB-DINARCH(1) model:



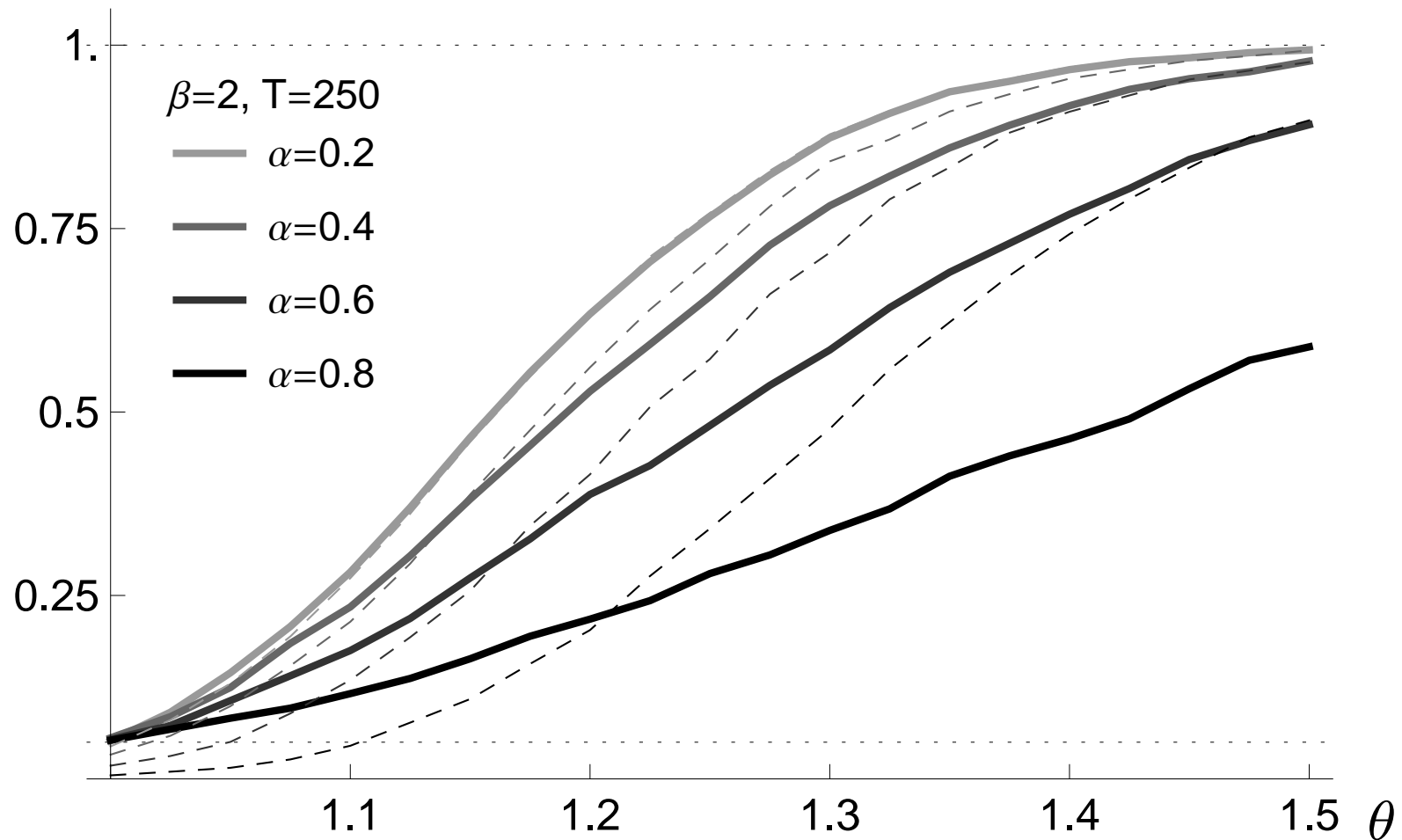
Power analysis w.r.t. NB-DINARCH(1) model:



Power analysis w.r.t. NB-DINARCH(1) model:



Power analysis w.r.t. NB-DINARCH(1) model:





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Conclusions

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... and Future Research

- Index of dispersion \hat{I} is simple and well-interpretable statistic for uncovering overdispersion.
- Distribution of \hat{I} severely influenced by autocorrelation
⇒ choose critical values carefully according to null model, power analysis has to consider degree of autocorrelation.
- Poisson INAR(1) vs. CPINAR(1) ✓,
Poisson INAR(1) vs. INARCH(1) ✓,
INARCH(1) vs. DINARCH(1):
rather strong degradation of power for large α .

Future research: adjustment for \hat{I} -test, or novel test.

Thank You for Your Interest!



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